



CULTURA MATEMATICA @ POLIMI
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La matematica dei terremoti

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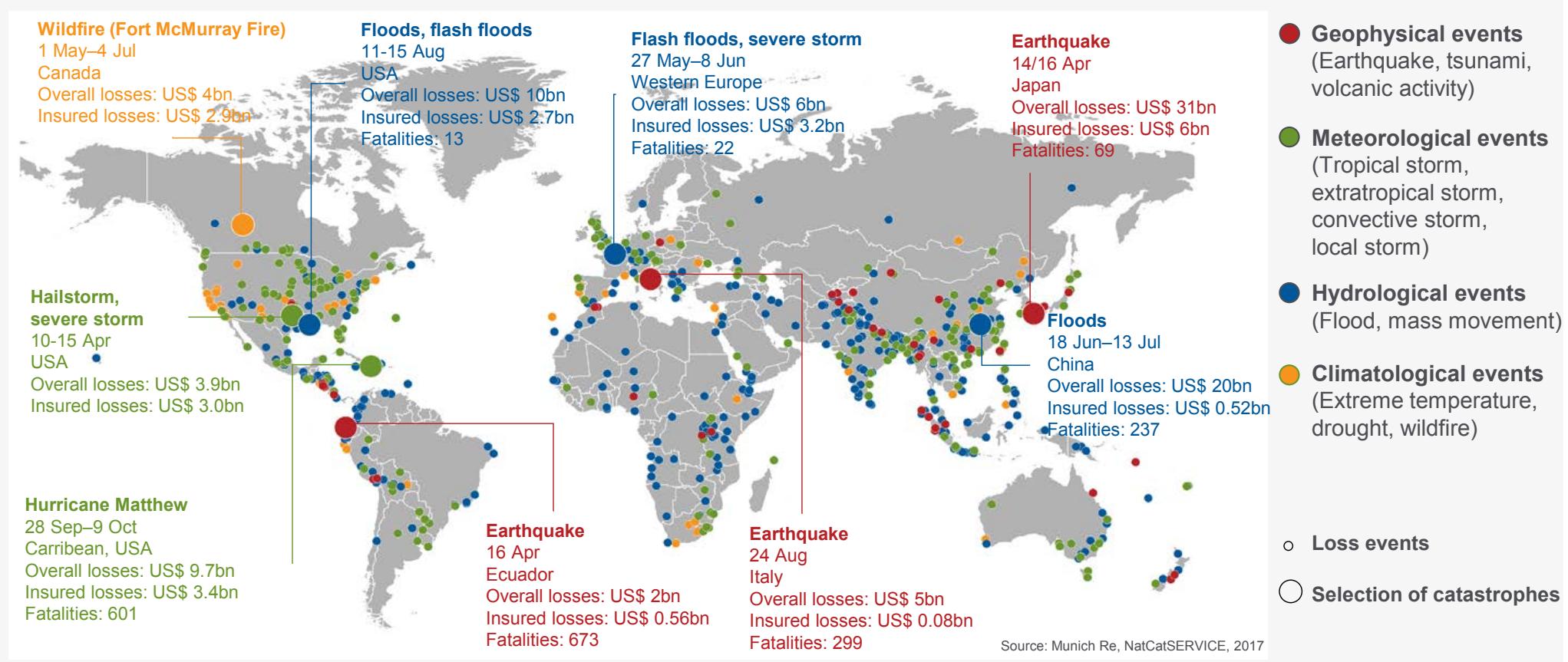
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Major Events and Losses in 2016

NatCatSERVICE

Loss events worldwide 2016 Geographical overview

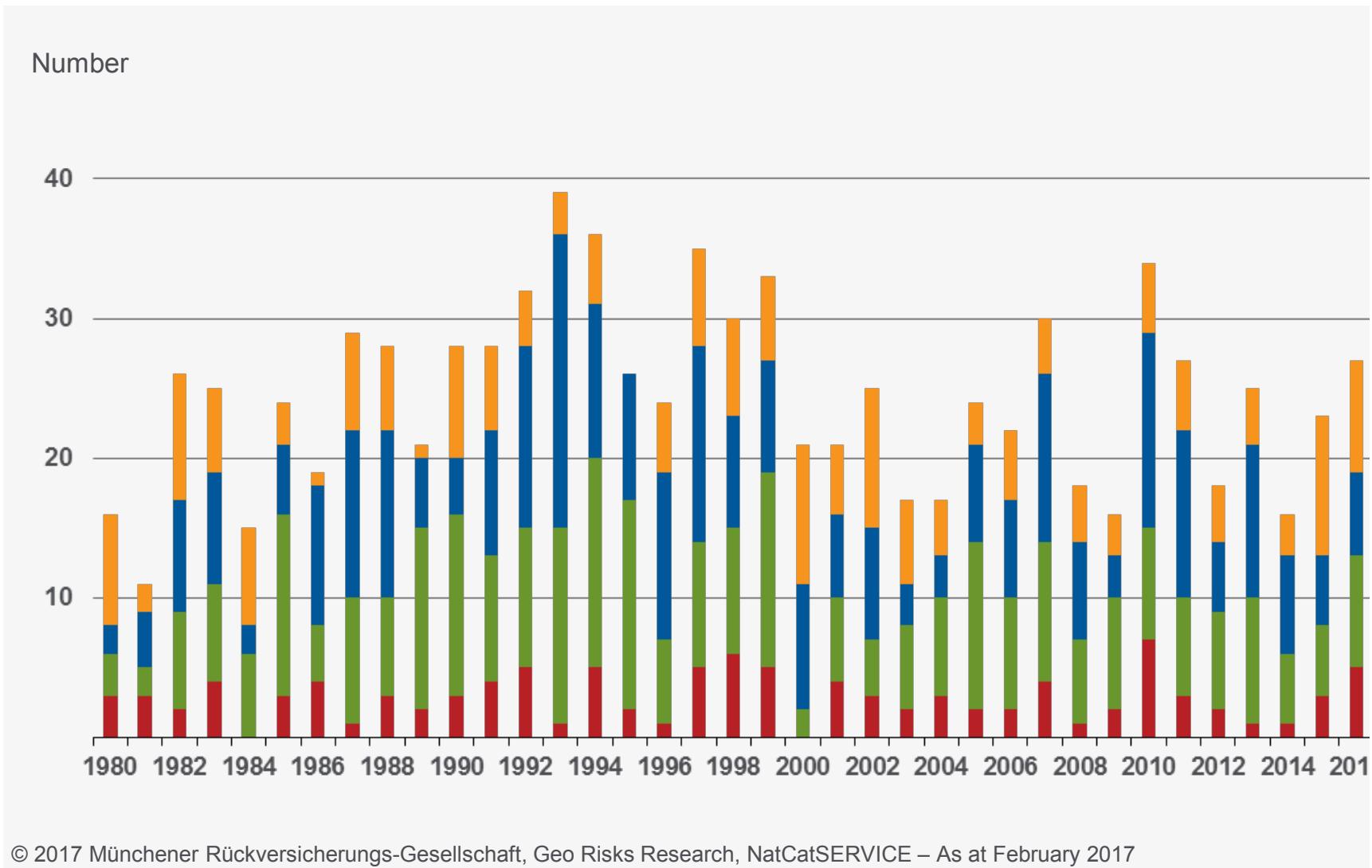


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1980 - 2016 at a glance

NatCatSERVICE

Loss events worldwide 1980 – 2016 Number of severe catastrophes by peril



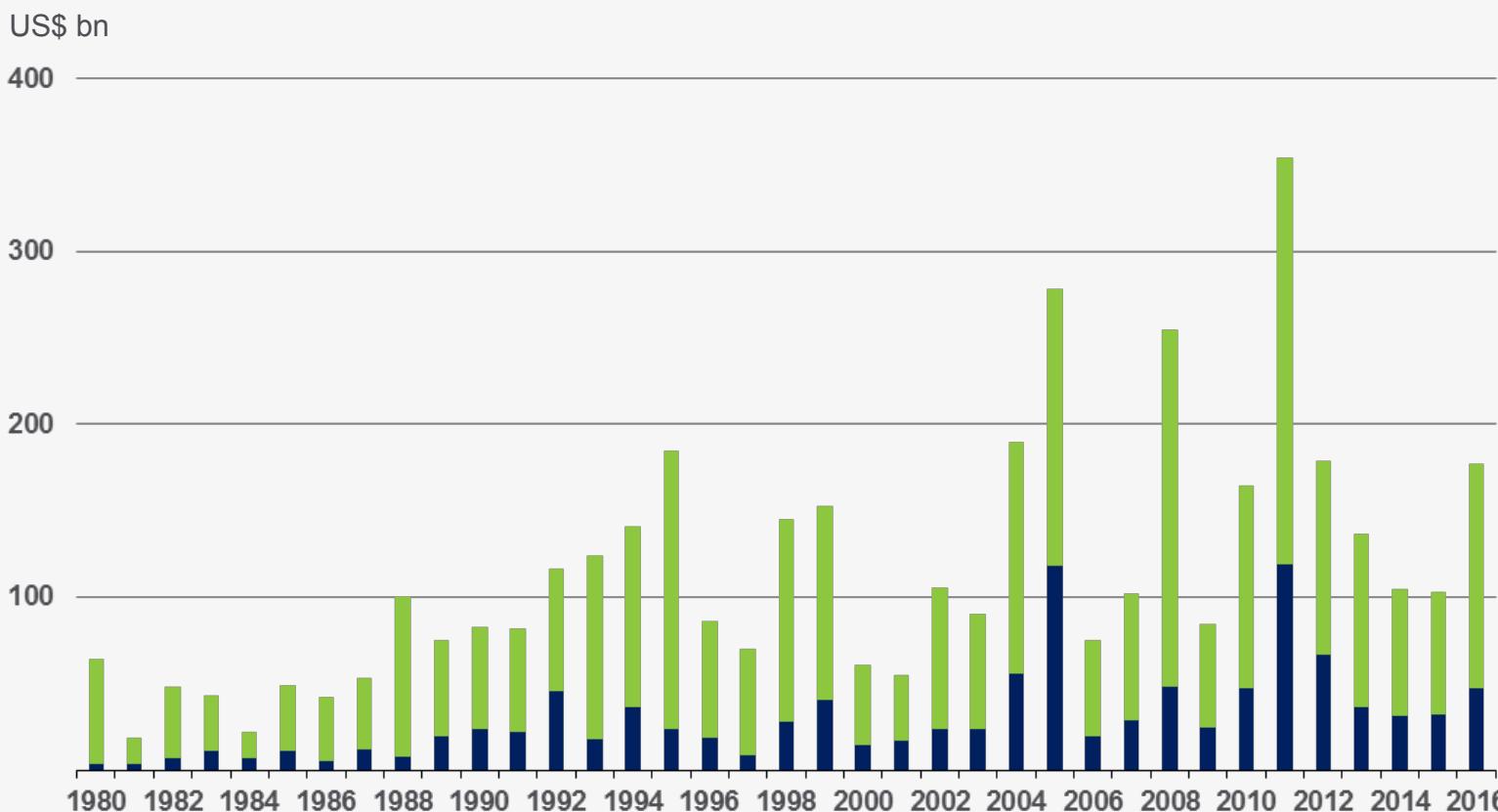
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Economical Impact

NatCatSERVICE



Loss events worldwide 1980 – 2016 Overall and insured losses



- Overall losses (in 2016 values)
- Insured losses (in 2016 values)

Inflation adjusted via country-specific consumer price index and consideration of exchange rate fluctuations between local currency and US\$.

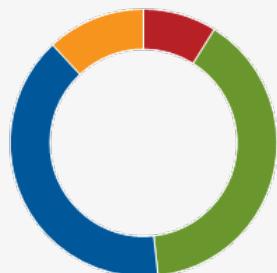
Distribution

NatCatSERVICE

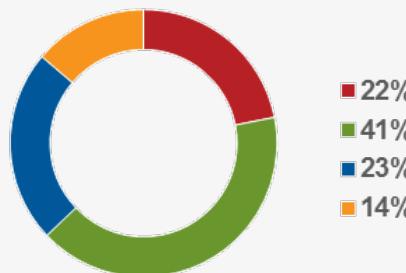
Loss events worldwide 1980 – 2016 Percentage distribution



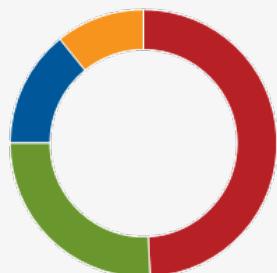
Number of relevant events: 16,500



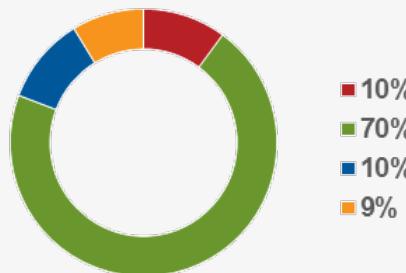
Overall losses: US\$ 4,200bn



Fatalities: 1,708,000



Insured losses: US\$ 1,100bn



■ Geophysical events
(Earthquake, tsunami,
volcanic activity)

■ Meteorological events
(Tropical storm,
extratropical storm,
convective storm,
local storm)

■ Hydrological events
(Flood, mass movement)

■ Climatological events
(Extreme temperature,
drought, forest fire)

Accounted events have caused at least one fatality and/or produced normalized losses \geq US\$ 100k, 300k, 1m, or 3m (depending on the assigned World Bank income group of the affected country).

Inflation adjusted via country-specific consumer price index and consideration of exchange rate fluctuations between local currency and US\$.

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10 Deadliest Events - Past 25 Years

NatCatSERVICE



Significant loss events worldwide 1980 – 2016 10 deadliest events

Date	Event	Affected area	Overall losses in US\$ m original values	Insured losses in US\$ m original values	Fatalities
26.12.2004	Earthquake, tsunami	Sri Lanka, Indonesia, Thailand, India, Bangladesh, Myanmar, Maldives, Malaysia	10,000	1,000	220,000
12.1.2010	Earthquake	Haiti	8,000	200	159,000
2-5.5.2008	Cyclone Nargis	Myanmar	4,000		140,000
29-30.4.1991	Tropical cyclone	Bangladesh	3,000	100	139,000
8.10.2005	Earthquake	Pakistan, India, Afghanistan	5,200	5	88,000
12.5.2008	Earthquake	China	85,000	300	84,000
July - Aug 2003	Heat wave	Europe	14,000	1,100	70,000
July - Sep 2010	Heat wave	Russian Federation			56,000
20.6.1990	Earthquake	Iran	7,100	100	40,000
26.12.2003	Earthquake	Iran	500	20	26,200

Source: Munich Re, NatCatSERVICE, 2017

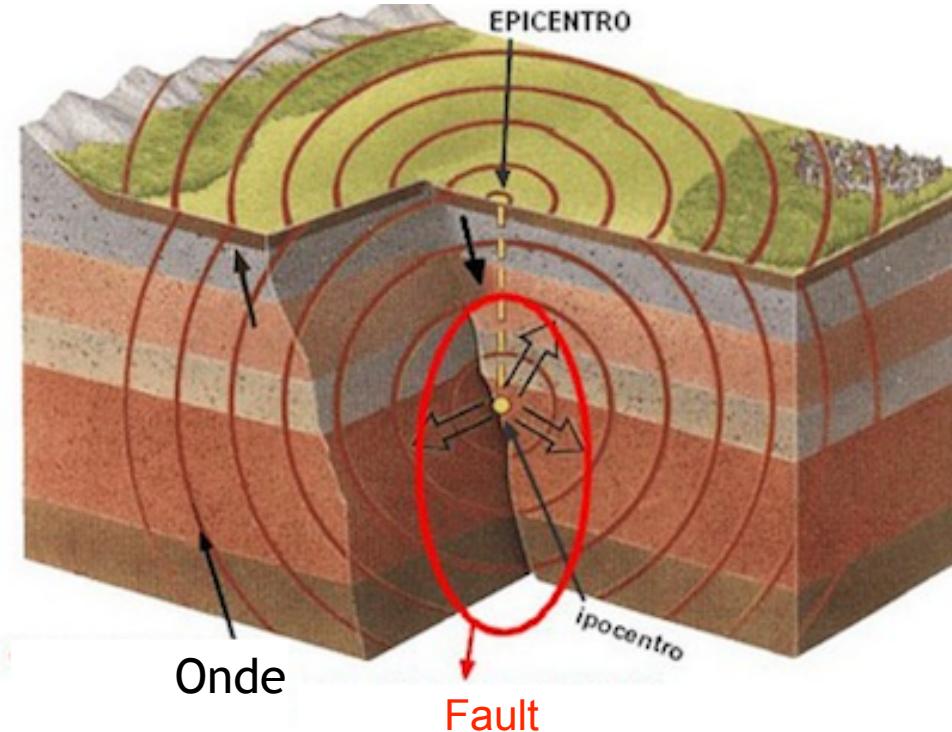
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Geophysics of earthquakes in a nutshell

Un terremoto è **liberazione di energia**.

Scatena in poche decine di secondi l'energia accumulata in decenni o secoli in un dato volume della crosta terrestre.

E' una prova di vitalità della Terra e si origina quando la crosta terrestre si separa in **due elementi che scivolano l'uno rispetto all'altro lungo un piano di faglia**.



Che cosa genera questo accumulo di energia? **Come e perché si attiva una faglia?** Capire da dove viene l'energia e che cosa ne caratterizza la dissipazione significa svelare più compiutamente l'origine dei terremoti e forse un giorno poterli prevedere.

Earthquakes

Pressione e temperatura aumentano scendendo all'interno della Terra, ma hanno l'effetto opposto: la **pressione rende le rocce più stabili**, mentre la **temperatura le rende più deboli**.

La conseguenza di questa antitesi fa sì che la crosta terrestre sia divisa in due parti caratterizzate dal diverso comportamento meccanico delle rocce.

Nella **crosta superiore, spessa in media 15 chilometri**, domina l'effetto della **pressione**, rendendo le rocce **stabili e fragili**, mentre nella crosta inferiore, corrispondente ai **sottostanti 15 chilometri**, prevale l'effetto della **temperatura**, che rende le rocce **deformabili e duttili**.

La transizione tra questi due strati a diverso comportamento meccanico, detta anche «**transizione fragile-duttile**», corrisponde alla massima resistenza delle rocce. Questa è la profondità a cui è necessaria **l'energia massima** per romperle.

Earthquakes

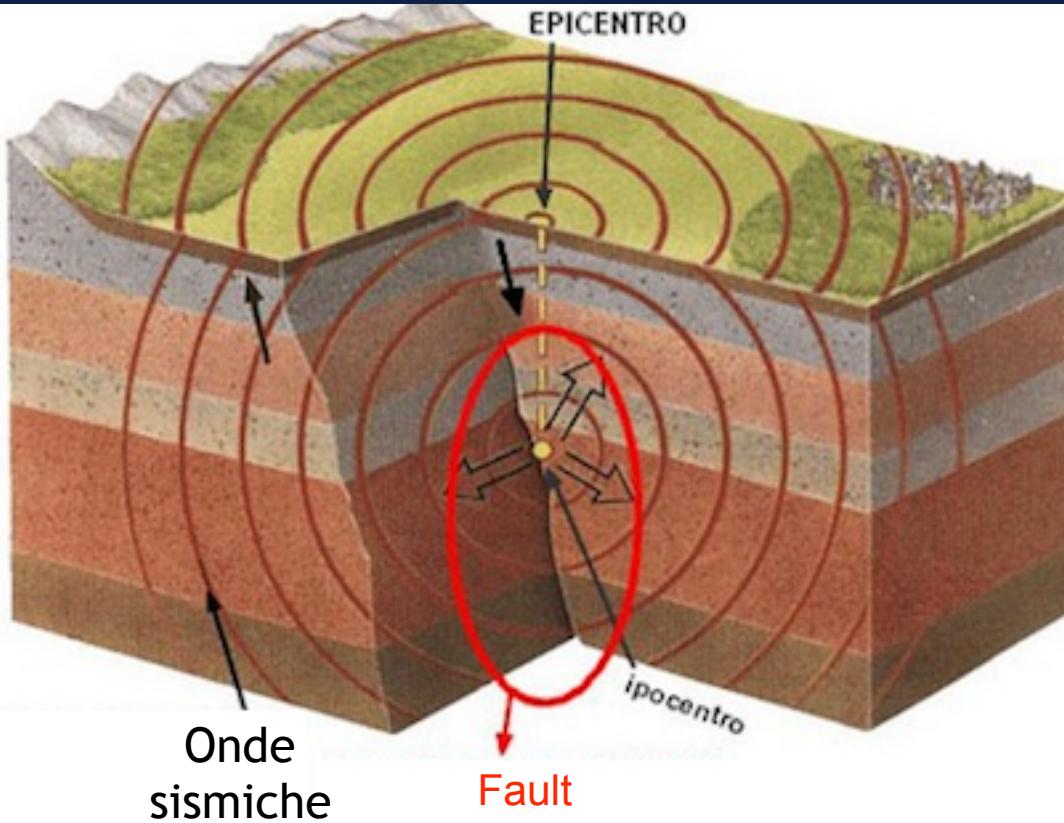
L'energia più grande liberata dai terremoti si concentra dunque a circa 15 km di profondità.

Nella **crosta inferiore** il movimento e la relativa deformazione delle rocce avvengono quasi in regime stazionario, in **modo assai lento ma inesorabile**, in un ambiente duttile.

Nella **crosta superiore fragile**, invece, il **movimento è episodico**: la faglia può rimanere bloccata per anni o per secoli, e rompersi con un forte terremoto, recuperando in pochi secondi buona parte del movimento effettuato dalla parte duttile sottostante nel lungo periodo, detto intersismico, non caratterizzato da forti terremoti.

Il **volumen fragile sovrastante**, rimanendo bloccata la faglia, **accumula sforzo**, diventando una sorta di **batteria energetica**.

Hypocenter, Epicenter



An earthquake is thus the release of **energy** caused by a **sudden slip on a fault** (a planar fracture or discontinuity in a volume of rock).

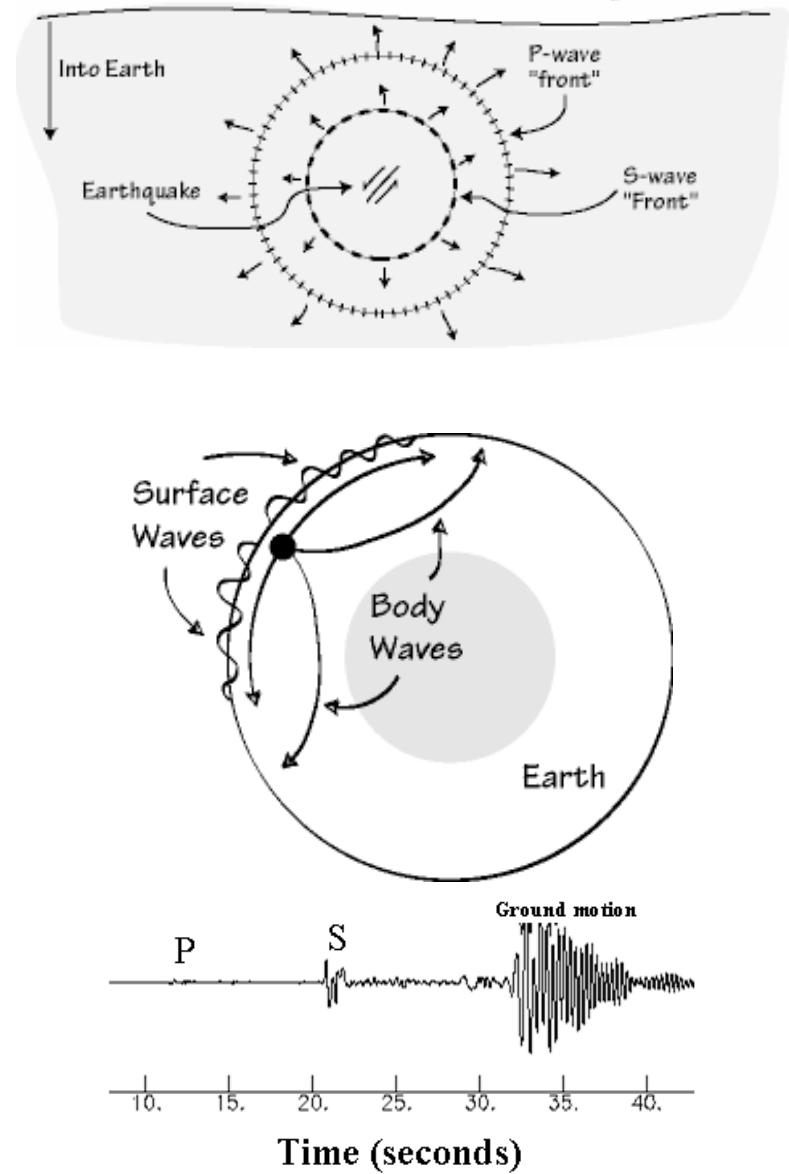
An earthquake's **hypocenter** is the position where the strain energy stored in the rock is first released, marking the point where the fault begins to rupture.

The fracture generates elastic waves, called **seismic waves**

Epicenter: the place of the earth's surface located on the vertical hypocenter

Geodynamics: P and S waves

- There are different kind of seismic waves. The most important ones are
 - ▶ Compressional or P (primary)
 - ▶ Transverse or S (secondary)
 - ▶ Love
 - ▶ Rayleigh
- An earthquake radiates P and S waves in all directions.
- The interaction of the P and S waves with Earth's surface → surface waves.
- P and S waves travel at different speeds (used to locate earthquakes)



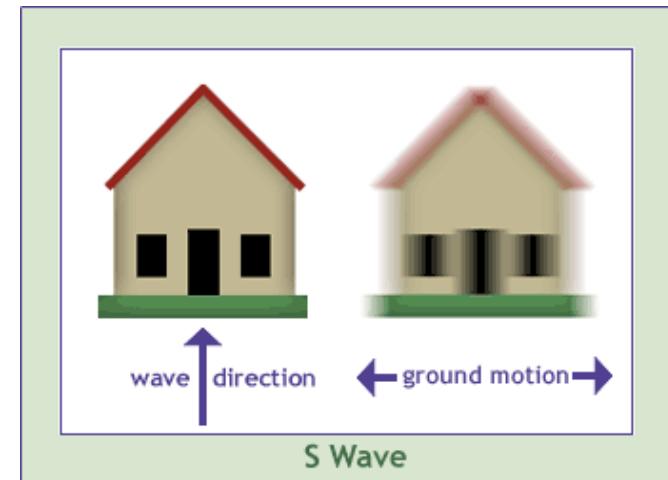
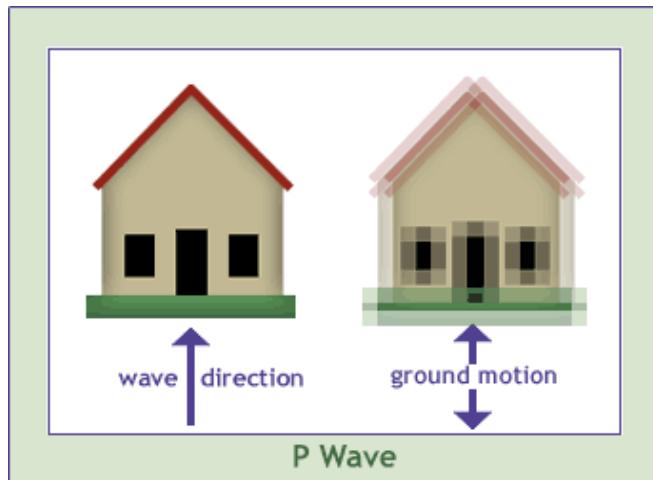
P and S waves - continues

P-Waves (Compressional)

- The ground is vibrated in the **direction** the wave is propagating.
- Travel through **all** types of **media**.
- $C_P = \sqrt{(\lambda + 2\mu)/\rho}$ (P-wave velocity)
- Typical speed: $\sim 1 \rightarrow 14$ km/sec

S-Waves (Transverse)

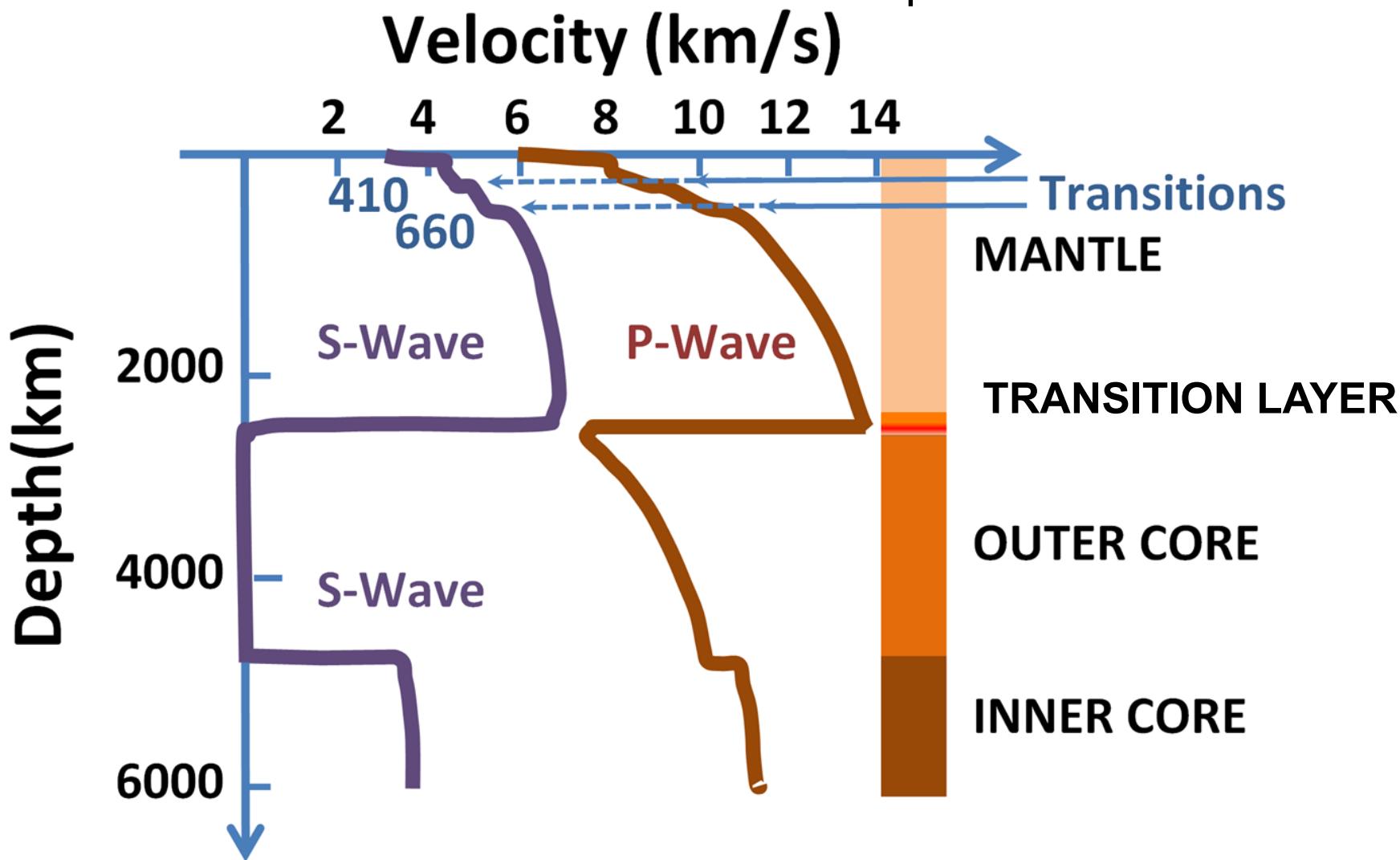
- The ground is vibrated in the **perpendicular direction** to that the wave is propagating.
- Travel **only** through **solid media**.
- $C_S = \sqrt{\mu/\rho}$ (S-wave velocity)
- Typical speed: $\sim 1 \rightarrow 8$ km/sec



Much of the damage close to an earthquake is the result of strong shaking caused by **S-waves**.

Speed of seismic waves in the Earth

Speeds of seismic waves in the Earth



GR Helffrich & BJ Wood (2002). "The Earth's Mantle". Nature. Macmillan Magazines. 412: 501

Measuring the size of an earthquake

The magnitude is a number that characterises the relative size of an earthquake. Magnitude is based on measurement of the maximum motion recorded by a seismograph.

Magnitudes are based on a logarithmic scale (base 10). Several scales have been defined:

1. Local magnitude - M_L
2. Surface-wave magnitude - M_s
3. Body-wave magnitude - M_b
4. Moment magnitude M_w .

Scales 1-3 have limited range and applicability and do not satisfactorily measure the size of the largest earthquakes.

The moment magnitude (M_w) scale, based on the concept of seismic moment, is uniformly applicable to all sizes of earthquakes.

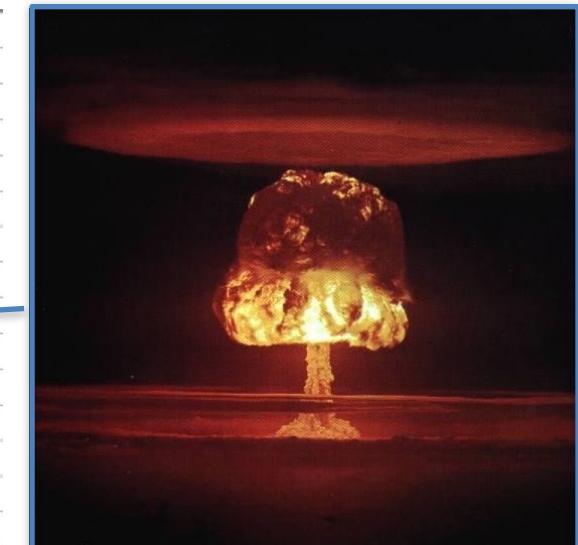
Source USGS

Moment Magnitude Scale (M_w)

$$M_w = (2/3) \log_{10} M_0 - C$$

Seismic moment [$N \cdot m$].
 (~ area of the rupture along the geologic fault where the earthquake occurred \times average displacement)

Magnitudo	TNT equivalente	Frequenza
0	1,0 chilogrammo	circa 8.000 al giorno
1	31,6 chilogrammi	
1,5	178,0 chilogrammi	
2	1,0 tonnellata	circa 1.000 al giorno
2,5	5,6 tonnellate	
3	31,6 tonnellate	circa 130 al giorno
3,5	178,0 tonnellate	
4	1.000,0 tonnellate	circa 15 al giorno
4,5	5.600,0 tonnellate	
5	31.600,0 tonnellate	2-3 al giorno
5,5	178.000,0 tonnellate	
6	1,0 milione di tonnellate	120 all'anno
6,5	5,6 milioni di tonnellate	
7	31,6 milioni di tonnellate	18 all'anno
7,5	178,0 milioni di tonnellate	
8	1,0 miliardo di tonnellate	1 all'anno
8,5	5,6 miliardi di tonnellate	
9	31,6 miliardi di tonnellate	1 ogni 20 anni
10	1.000,0 miliardi di tonnellate	Mai registrata



Bomba Hiroshima.
 TNT equivalente:
 15.000 tonnellate

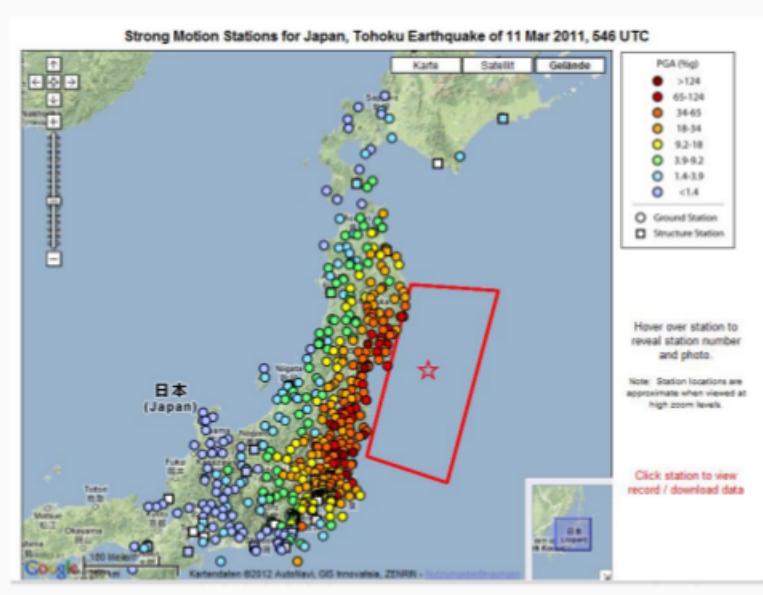
An increase of one step on the logarithmic scale corresponds to a $10^{1,5} \approx 32$ times increase in the amount of energy released

Earthquakes: large vs medium (Moment magnitude M_w)

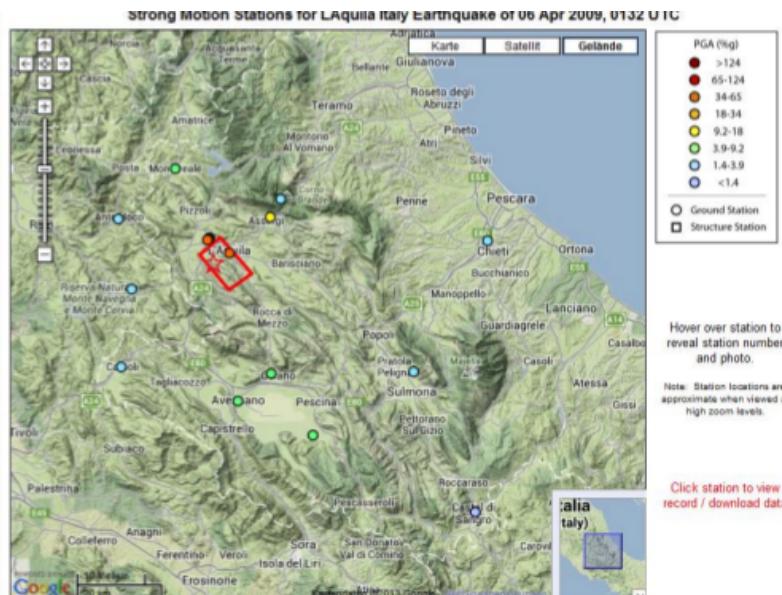
Maule, Mw 8.8, 27.02.2010



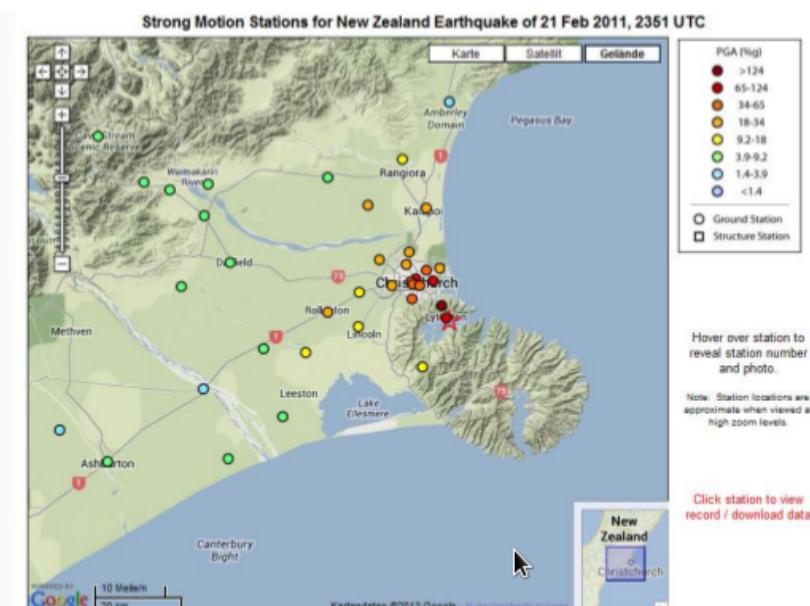
Tohoku, Mw 9.0, 11.03.2011



L'Aquila, Mw 6.1, 06.04.2009



Christchurch Mw 6.3, 22.02.2011



Strong motion stations: Peak Ground Acceleration (PGA)

Italian seismicity: earthquakes since 1900 ($M_w \geq 5.8$)



Ground motion prediction (GMP)

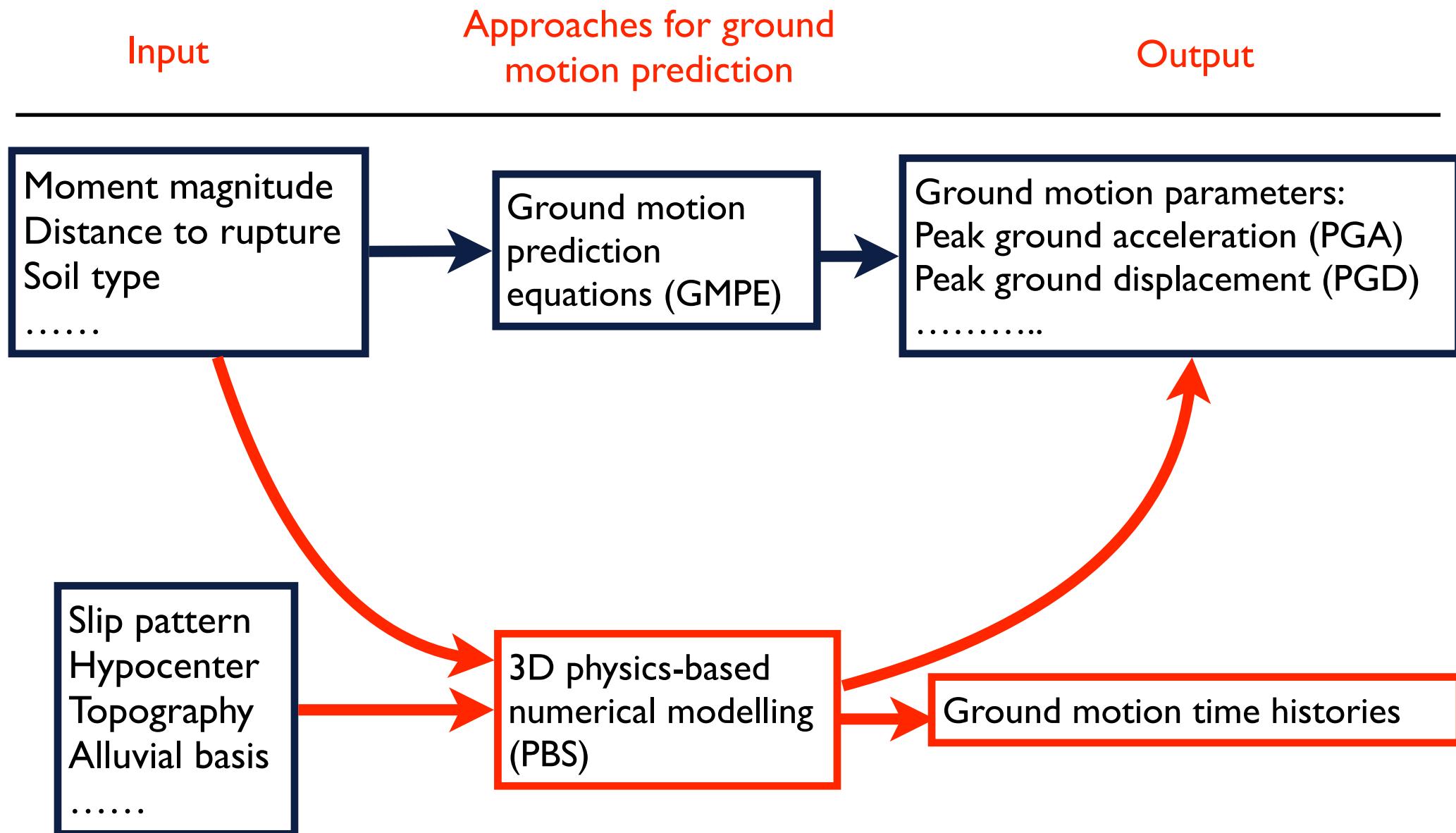
Tools for **ground motion prediction (GMP)** are one of the key ingredients in seismic hazard analysis, both within probabilistic and deterministic frameworks.

Objective: provide estimates of the expected ground motion at a site, given an earthquake of known magnitude, distance, faulting style, etc.

A variety of procedures for GMP relying on different information detail on the seismic source and propagation path on one side, and, on the other side, providing different levels of output, either in terms of peak values of ground motion or of an entire time history.

Proposed procedures range from the empirical **Ground Motion Prediction Equations (GMPE)**, typically calibrated on the instrumental observations from real earthquakes, up to complex 3D Physics-Based numerical Simulations (**PBS**).

Approaches for ground motion prediction



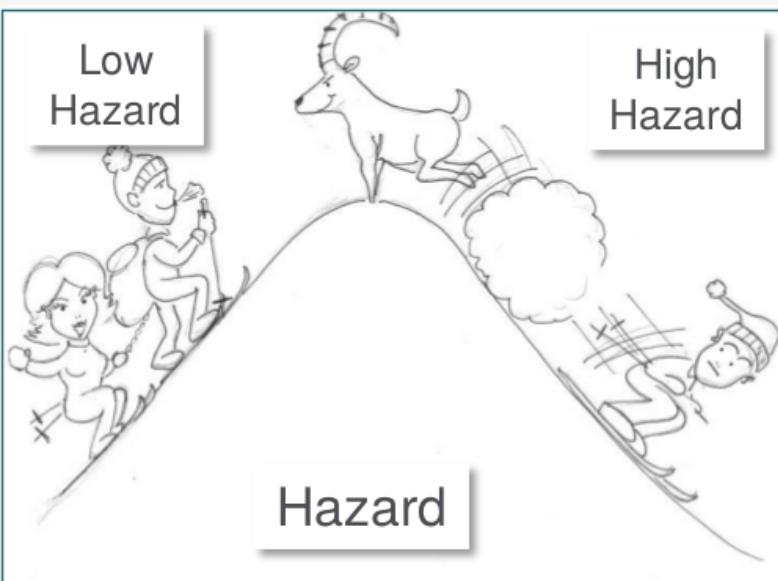
Seismic risk in nutshell

Assess the vulnerability of existing buildings is an essential step to improve seismic risk management

Hazard: probability that an earthquake will occur in a given geographic area within a given window of time, and with ground motion intensity exceeding a given threshold

Vulnerability: inability of buildings to withstand the effects of seismic forces

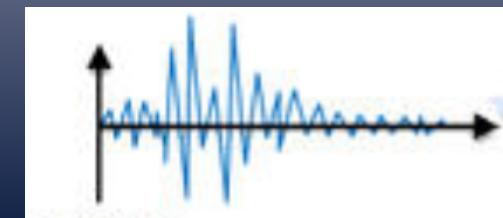
Exposure: possibility of damage in economic terms, to cultural heritage or the loss of human lives



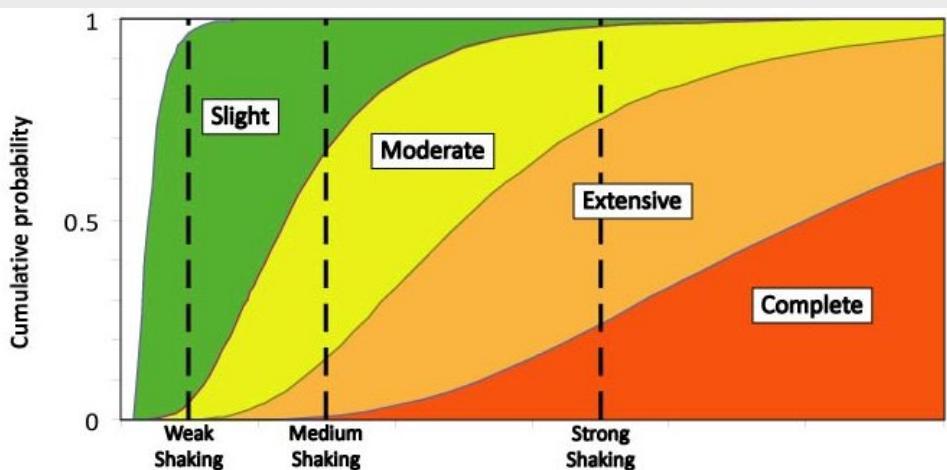
From ground motion prediction to seismic vulnerability of structures

Numerical modeling

Ground motion time histories/parameters



Fragility curves: conditional probability of failure at a given seismic response parameter (PGA, PGV,)

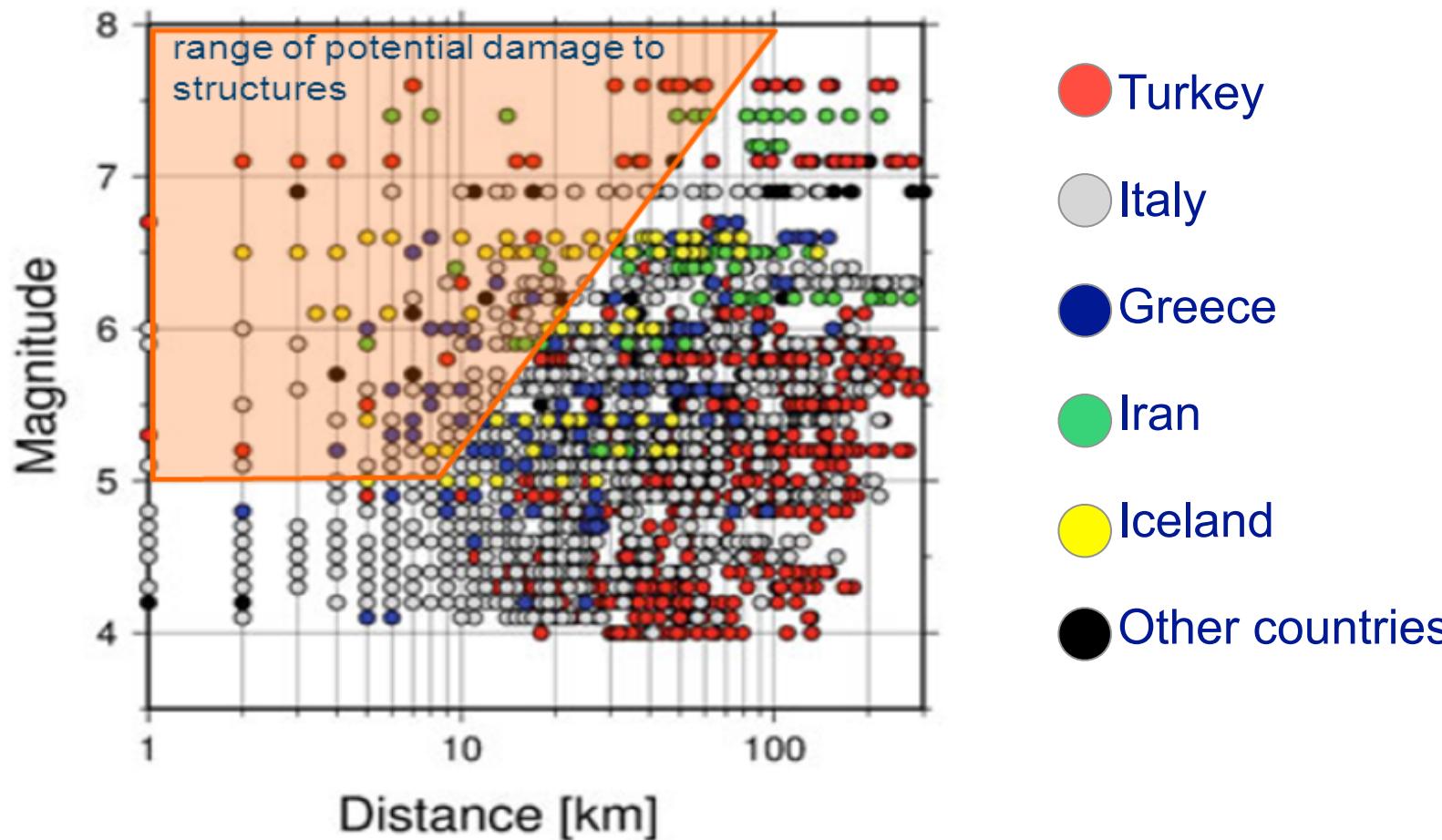


Structural analysis based on mathematical/numerical modelling of the building



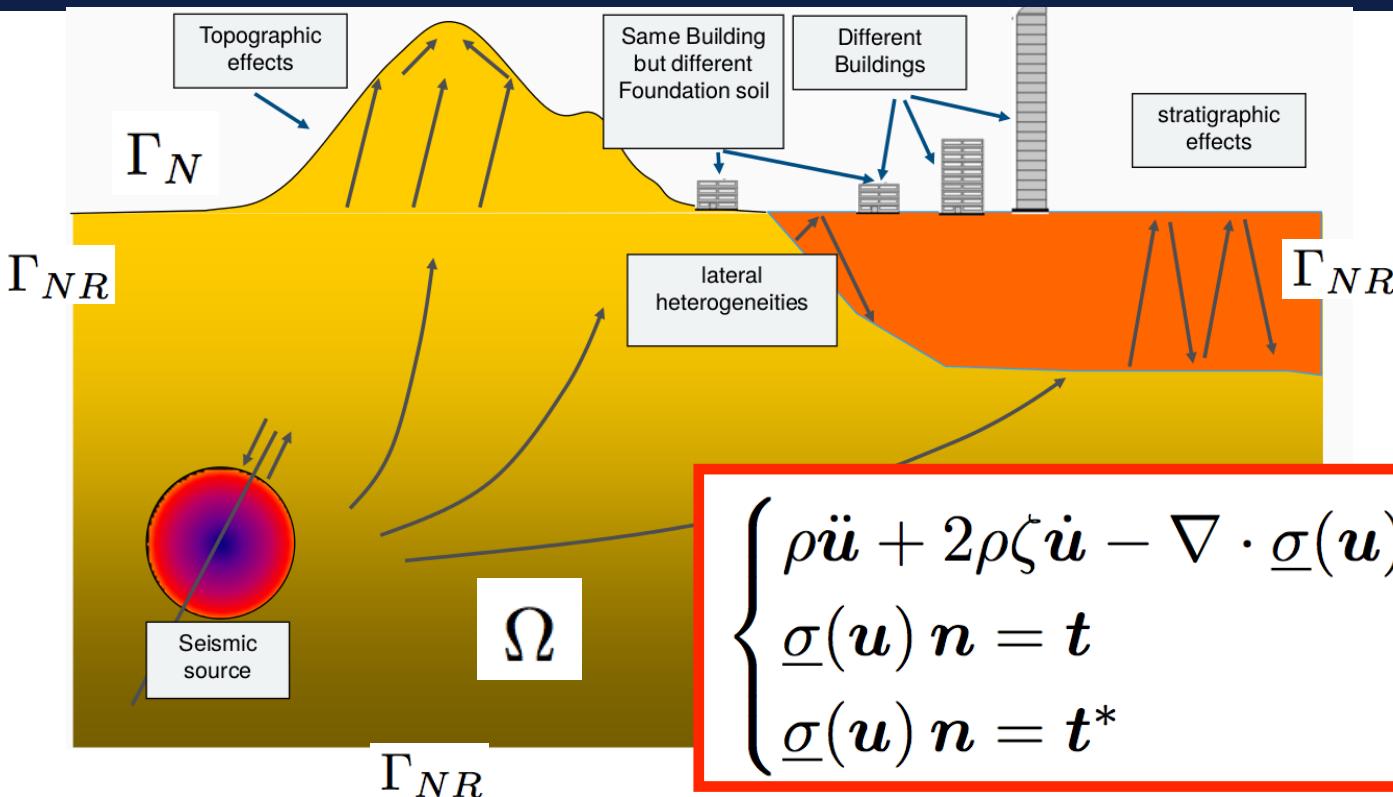
Limitations of Ground Motion Prediction Equations

The amount of available earthquake records



Magnitude and distance range covered by the strong motion database for calibration of pan-European ground motion prediction equations

PBS - The mathematical model



$$\begin{cases} \rho \ddot{\mathbf{u}} + 2\rho\zeta\dot{\mathbf{u}} - \nabla \cdot \underline{\sigma}(\mathbf{u}) + \rho\zeta^2\mathbf{u} = \mathbf{f} & \text{in } \Omega \\ \underline{\sigma}(\mathbf{u}) \mathbf{n} = \mathbf{t} & \text{on } \Gamma_N \\ \underline{\sigma}(\mathbf{u}) \mathbf{n} = \mathbf{t}^* & \text{on } \Gamma_{NR} \end{cases}$$

$\mathbf{u} = \mathbf{u}(\mathbf{x}, t)$ is the displacement field

$\underline{\sigma}(\mathbf{u}) = \lambda \text{tr}(\underline{\epsilon}(\mathbf{u})) \underline{I} + 2\mu \underline{\epsilon}(\mathbf{u})$ is the stress tensor

$\zeta \geq 0$ is a damping factor ($\sim 0.01 \text{ s}^{-1}$)

$\lambda = \lambda(\mathbf{x})$ $\mu = \mu(\mathbf{x})$ are the first/second Lame' coefficients

The term $2\rho\zeta\dot{\mathbf{u}} + \rho\zeta^2\mathbf{u}$ models the visco-elastic effects

ρ is the medium density

$\mathbf{t}^* = \mathbf{t}^*(\mathbf{x}, t)$ is a fictitious traction

$\mathbf{t} = \mathbf{t}(\mathbf{x}, t)$ is a given traction

$$c_P = \sqrt{\frac{\lambda + 2\mu}{\rho}}, \quad c_S = \sqrt{\frac{\mu}{\rho}},$$

compressional/shear wave velocities

Weak form

$\forall t \in (0, T]$ find $\mathbf{u}(t) \in \mathbf{V} = \{\mathbf{v} \in \mathbf{H}^1(\Omega), \mathbf{v} = \mathbf{0} \text{ on } \Gamma_D\}$ such that

$$(\rho \ddot{\mathbf{u}}(t), \mathbf{v})_{\Omega} + (2\rho\zeta \dot{\mathbf{u}}(t), \mathbf{v})_{\Omega} + (\rho\zeta^2 \mathbf{u}, \mathbf{v})_{\Omega} + \mathcal{A}(\mathbf{u}(t), \mathbf{v}) = \mathcal{F}(\mathbf{v}) \quad \forall \mathbf{v} \in V$$

supplemented with the initial conditions $\mathbf{u}(0) = \mathbf{u}_0$ and $\dot{\mathbf{u}}(0) = \mathbf{v}_0$

$$\mathcal{A}(\mathbf{u}, \mathbf{v}) = (\underline{\sigma}(\mathbf{u}), \underline{\varepsilon}(\mathbf{v}))_{\Omega}, \quad \mathcal{F}(\mathbf{v}) = (\mathbf{f}, \mathbf{v})_{\Omega} + \langle \mathbf{t}, \mathbf{v} \rangle_{\Gamma_N} + \langle \mathbf{t}^*, \mathbf{v} \rangle_{\Gamma_{NR}}.$$

Requirements on the numerical solution

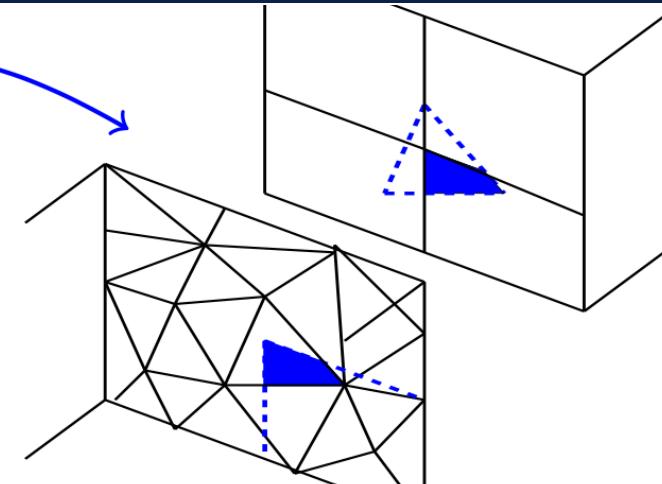
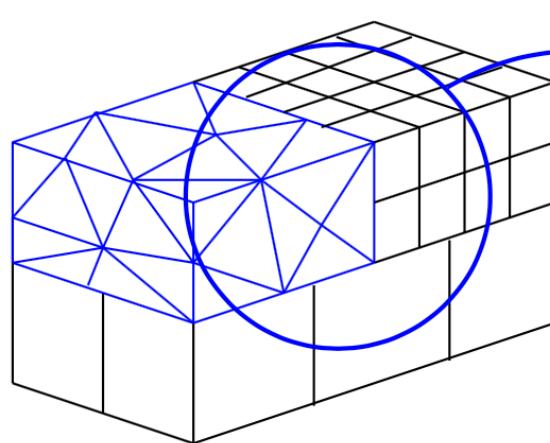
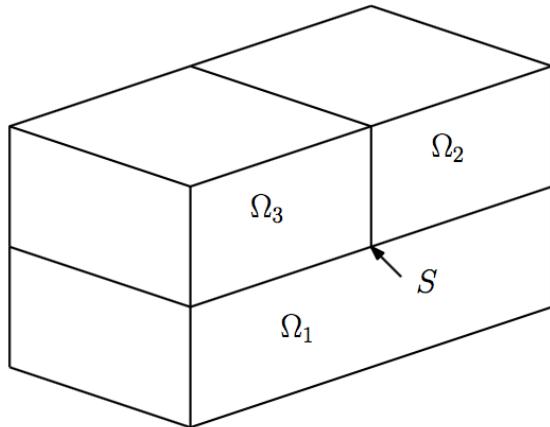
- Accurate description of the behaviour at material interfaces
 - ➡ high-order accuracy
- Waves are typically propagated over many periods of time
 - ➡ control the numerical dispersion and dissipation errors
- Complex geometries and strong contrasts in wave speeds
 - ➡ methods that accommodate non-conforming grids
- The size of the bodies excited is large relative to the wavelengths of interests
 - ➡ efficient and scalable implementation for parallel computing

**Discontinuous
Galerkin
Spectral
Element
methods
(DGSEM)**

Discontinuous Galerkin methods for wave propagation problems

[Riviere, Wheeler, 2003], [Riviere, Shaw, Wheeler, Whiteman, 2003],[Kaser, Dumbser, 2006], [Chung, Enquist, 2006], [Riviere, Shaw, Whiteman, 2007], [De Basabe, Sen, 2007], [Dumbser, Kaser, Toro, 2007], [de Basabe, Sen, Wheeler, 2008], [Delcourte, Fezoui, Glinsky-Olivier, 2009],[Grote, Diaz, 2009], [Wilcox, Stadler, Burstedde, Ghattas, 2010], [Etienne, Chaljub, Virieux, Glinsky, 2010], [Antonietti, Mazzieri, Rapetti, Quarteroni, 2012], [Pelties, Puente, Ampuero, Brietzke, Kaser, 2012], [Mazzieri, Stupazzini, Smerzini, Guidotti, 2013], [Peyrusse, Glinsky, Gelis, Lanteri, 2014], [Antonietti, Ayuso, Mazzieri, Quarteroni, 2015], [Antonietti, Marcati, Mazzieri, Quarteroni, 2015], [Paolucci, Mazzieri, Smerzini, 2015], [Mercerat, Glinsky, 2015], [Antonietti, Dal Santo, Mazzieri, Quarteroni, 2016], [Ferroni, Antonietti, Mazzieri, Quarteroni, 2016], [Antonietti, Ferroni, Mazzieri, Paolucci, Quarteroni, Smerzini, Stupazzini, 2017]

Mesh partition and subspaces



Ω is partitioned into macro-regions Ω_ℓ

Each macro-region is meshed independently by a conforming hexahedral/tetrahedral partition \mathcal{T}_{h_ℓ}

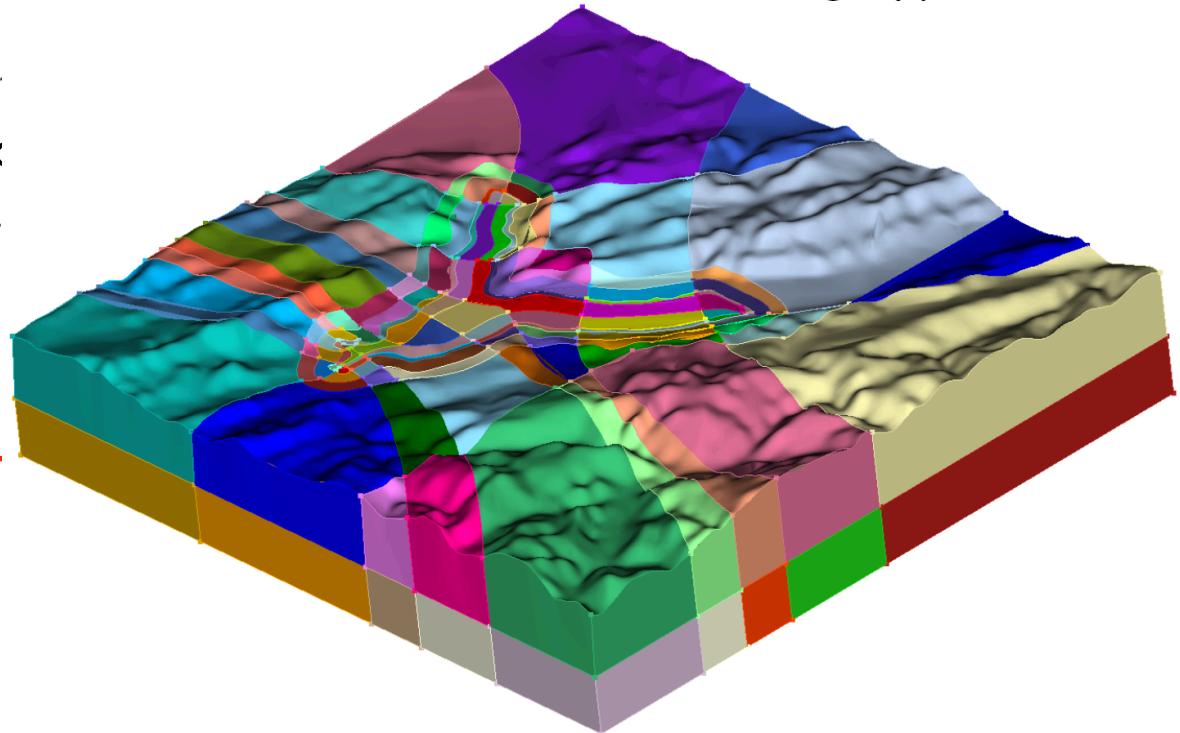
DG paradigm at the interfaces

A function in V_{DG} is

continuous in each macro-region

discontinuous across the skeleton

a polynomial of degree N_ℓ in each mesh-element of \mathcal{T}_{h_ℓ}



The semidiscrete scheme

$\forall t \in (0, T]$, find $\mathbf{u}_h = \mathbf{u}_h(t) \in V_{\text{DG}}$ such that

$$\sum_{\Omega_\ell} (\rho \ddot{\mathbf{u}}_h(t), \mathbf{v})_{\Omega_\ell} + \sum_{\Omega_\ell} (2\rho\zeta \dot{\mathbf{u}}_h(t), \mathbf{v})_{\Omega_\ell} + \mathcal{A}_h(\mathbf{u}_h(t), \mathbf{v}) + \sum_{\Omega_\ell} (\rho\zeta^2 \mathbf{u}_h, \mathbf{v})_{\Omega_\ell} = \mathcal{F}_h(\mathbf{v})$$

$$\mathcal{A}_h(\mathbf{u}, \mathbf{v}) = \sum_{\Omega_\ell} (\underline{\sigma}(\mathbf{u}), \underline{\varepsilon}(\mathbf{v}))_{\Omega_\ell} - \langle \{\underline{\sigma}(\mathbf{u})\}, [\![\mathbf{v}]\!] \rangle_{\mathcal{F}_h^I} - \langle [\![\mathbf{u}]\!], \{\underline{\sigma}(\mathbf{v})\} \rangle_{\mathcal{F}_h^I} + \langle \eta [\![\mathbf{u}]\!], [\![\mathbf{v}]\!] \rangle_{\mathcal{F}_h^I},$$

$$\mathcal{F}_h(\mathbf{v}) = \sum_{\Omega_\ell} (\mathbf{f}, \mathbf{v})_{\Omega_\ell} + \langle \mathbf{t}, \mathbf{v} \rangle_{\mathcal{F}_h^N} + \langle \mathbf{t}^*, \mathbf{v} \rangle_{\mathcal{F}_h^{NR}}$$

Stability

Assume $\mathbf{t} = \mathbf{0}$ and $\Gamma_{NR} = \emptyset$

Theorem(Stability). *Let, for any time $t \in (0, T]$ and for a sufficiently large penalty parameter $\mathbf{u}_h(t) \in V_{\text{DG}}$ be the semi-discrete solution. If $\mathbf{f} \in L^2(0, T; \mathbf{L}^2(\Omega))$, then*

$$\|\mathbf{u}_h(t)\|_{\mathcal{E}} \lesssim \|\mathbf{u}_h(0)\|_{\mathcal{E}} + \int_0^t \|\mathbf{f}(\tau)\|_{0,\Omega} d\tau, \quad 0 < t \leq T.$$

$$\|\mathbf{u}_h(t)\|_{\mathcal{E}}^2 = \|\rho^{1/2} \dot{\mathbf{u}}_h(t)\|_{0,\Omega}^2 + \|\rho^{1/2} \zeta \mathbf{u}_h(t)\|_{0,\Omega}^2 + \sum_{\ell} \|\underline{D}^{1/2} \underline{\varepsilon}(\mathbf{v})\|_{0,\Omega_\ell}^2 + \|\eta^{1/2} [\![\mathbf{v}]\!]\|_{0,\mathcal{F}_h^I}^2$$

Error estimates for the semidiscrete formulation

Theorem (*A-priori error estimate in the energy norm.*) If $\mathbf{u}(t)|_{\Omega_\ell}, \dot{\mathbf{u}}(t)|_{\Omega_\ell}, \ddot{\mathbf{u}}(t)|_{\Omega_\ell} \in \mathbf{H}^{s_\ell}(\Omega_\ell)$, $\ell = 1, \dots, L$, $s_\ell \geq 2$, then

$$\begin{aligned} \sup_{t \in [0, t]} \|e_h\|_{\mathcal{E}}^2 &\lesssim \sup_{t \in [0, T]} \left\{ \sum_{\Omega_\ell} \frac{h_\ell^{2 \min(s_\ell, N_\ell+1)-2}}{N_\ell^{2s_\ell-3}} (\|\dot{\mathbf{u}}\|_{s_\ell, \Omega_\ell}^2 + \|\mathbf{u}\|_{s_\ell, \Omega_\ell}^2) \right\} \\ &\quad + \int_0^T \sum_{\Omega_\ell} \frac{h_\ell^{2 \min(s_\ell, N_\ell+1)-2}}{N_\ell^{2s_\ell-3}} (\|\ddot{\mathbf{u}}\|_{s_\ell, \Omega_\ell}^2 + \|\dot{\mathbf{u}}\|_{s_\ell, \Omega_\ell}^2) d\tau. \end{aligned}$$

Remark If $h = \max_{\Omega_\ell} h_\ell \approx h_\ell$, $N_\ell = N$ for any $\ell = 1, \dots, L$, and the exact solution belong to $\mathbf{H}^s(\Omega)$, with $s \geq N + 1$,

$$\sup_{t \in [0, T]} \|e_h(t)\|_{\mathcal{E}}^2 \lesssim \frac{h^{2 \min(s, N+1)-2}}{N^{2s-3}} \left(\sup_{t \in [0, T]} \{ \|\dot{\mathbf{u}}\|_{s, \Omega}^2 + \|\mathbf{u}\|_{s, \Omega}^2 \} + \int_0^T (\|\ddot{\mathbf{u}}\|_{s, \Omega}^2 + \|\dot{\mathbf{u}}\|_{s, \Omega}^2) d\tau \right)$$

Fully discrete formulation

The semi-discrete algebraic formulation reads as

$$\ddot{\mathbf{M}}\dot{\mathbf{U}}(t) + (\mathbf{M}_2 + \mathbf{S})\dot{\mathbf{U}}(t) + (\mathbf{A} + \mathbf{M}_3 + \mathbf{R})\mathbf{U}(t) = \mathbf{F}(t)$$

$$\mathbf{U}(0) = \mathbf{U}^0$$

$$\dot{\mathbf{U}}(0) = \mathbf{V}^0$$

Second order accurate
Conditionally stable (CFL)

$$\Delta t \leq C_{CFL} \frac{h}{c_P N^2}$$

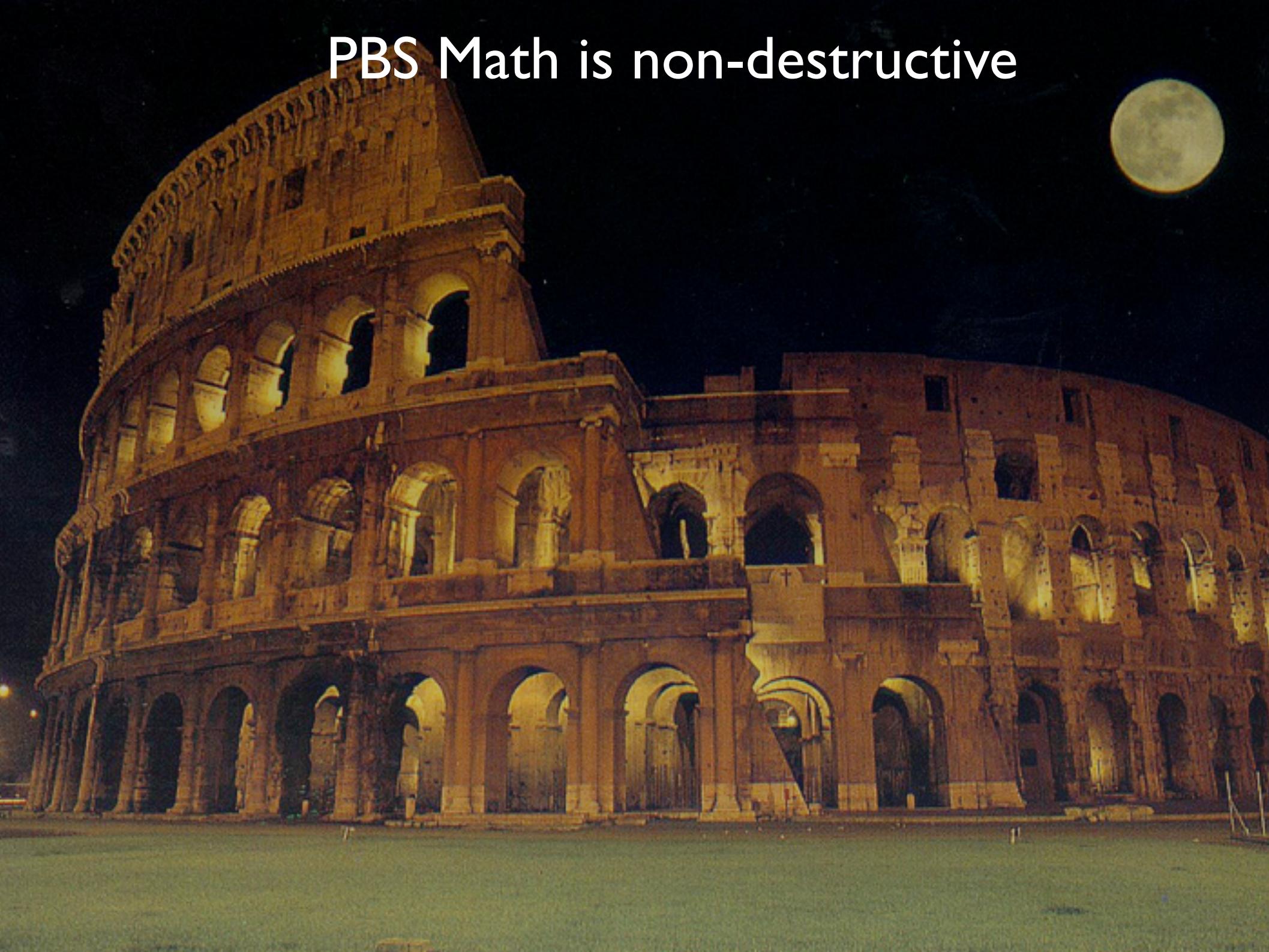
Leap-frog time integration scheme

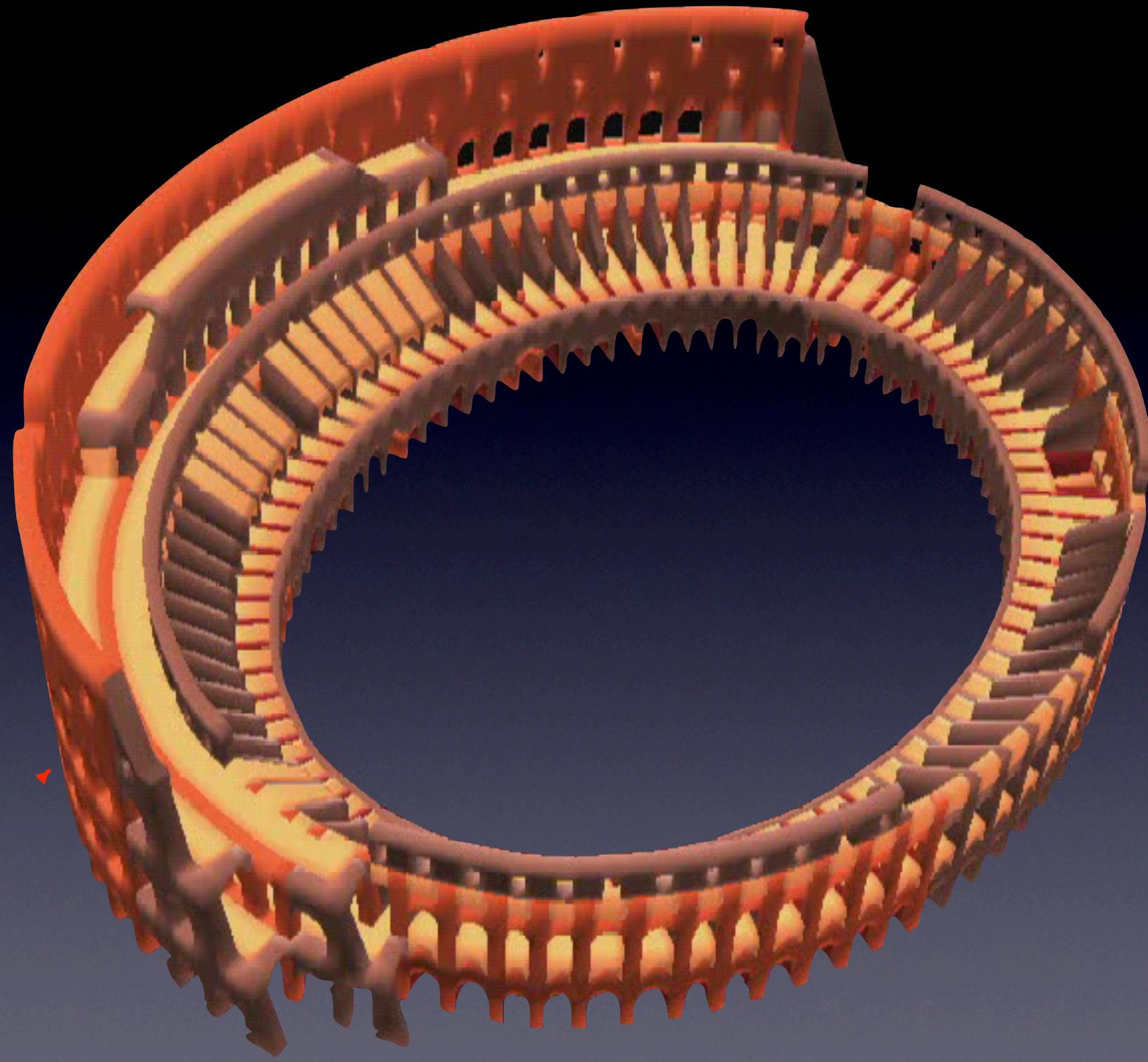
$$\mathbf{M}\mathbf{U}^1 = (\mathbf{M} - \frac{\Delta t^2}{2}\mathbf{Q})\mathbf{U}^0 + (\Delta t\mathbf{M} - \frac{\Delta t^2}{2}\mathbf{K})\mathbf{V}^0 + \frac{\Delta t^2}{2}\mathbf{F}^0,$$

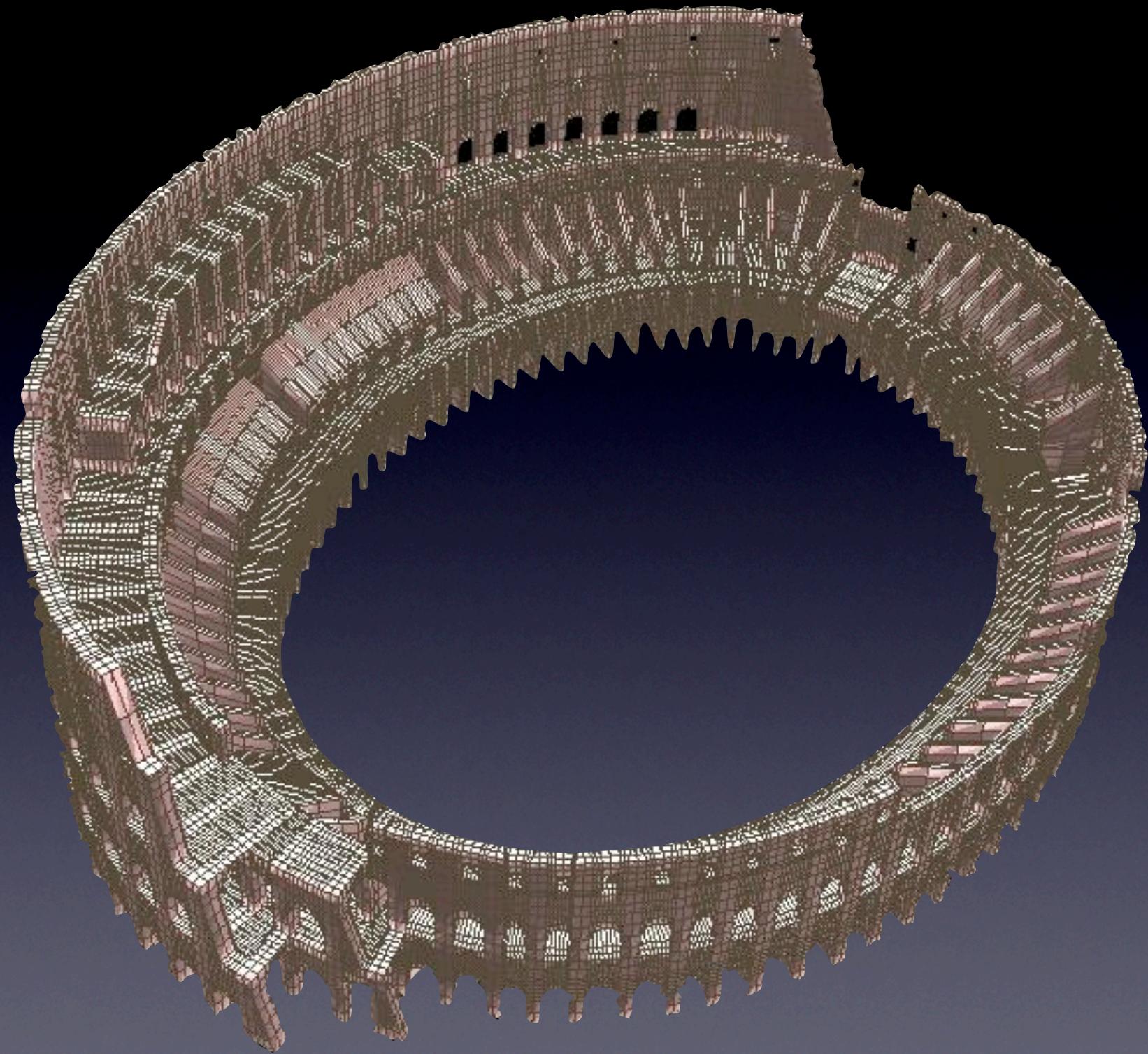
$$(\mathbf{M} + \frac{\Delta t}{2}\mathbf{K})\mathbf{U}^{n+1} = (2\mathbf{M} - \Delta t^2\mathbf{Q})\mathbf{U}^n + (\mathbf{M} - \frac{\Delta t}{2}\mathbf{K})\mathbf{U}^{n-1} + \Delta t^2\mathbf{F}^n, \quad n = 1, \dots, N_T - 1$$

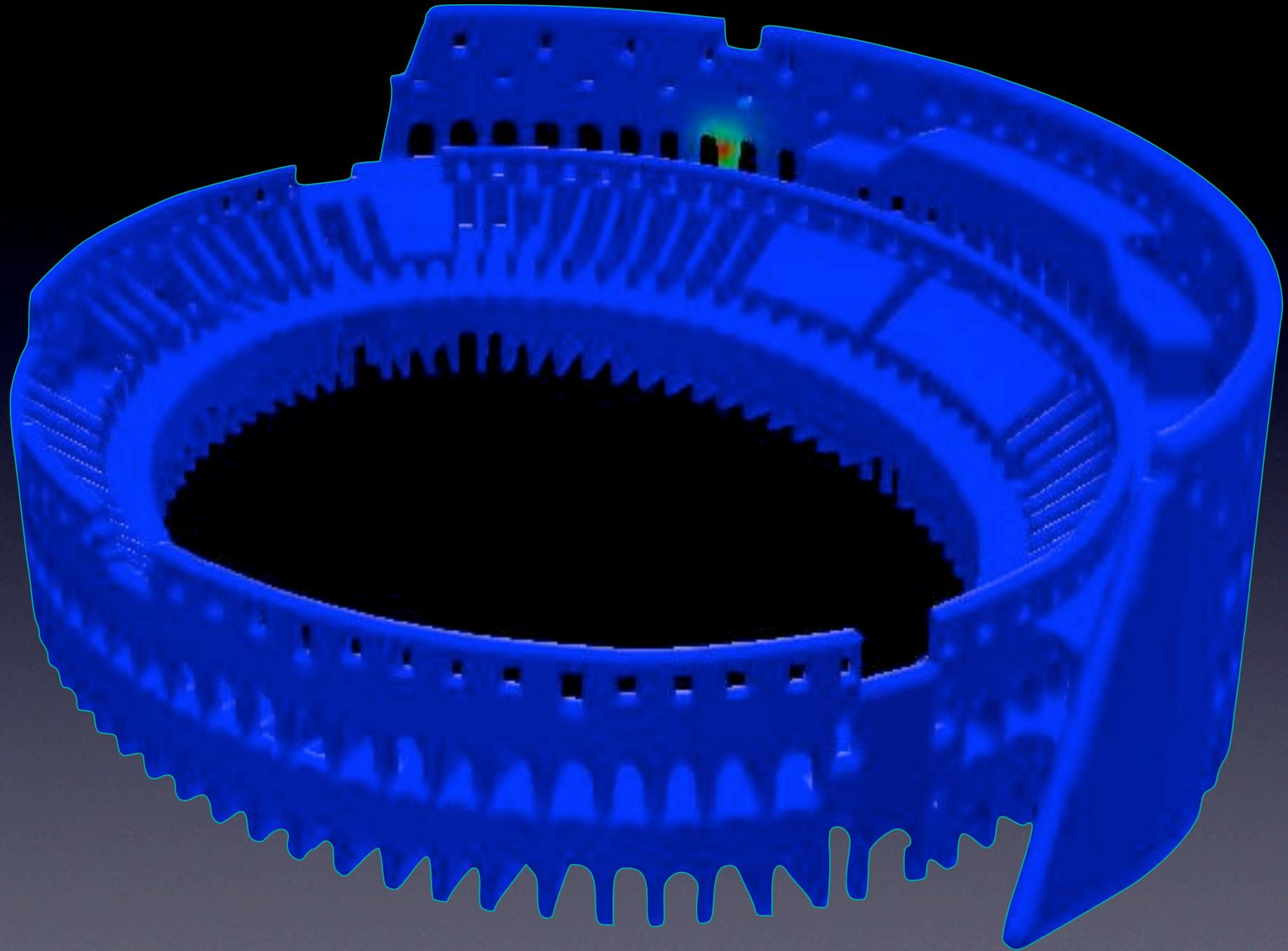
with $\mathbf{K} = \mathbf{M}_2 + \mathbf{S}$ and $\mathbf{Q} = \mathbf{A} + \mathbf{M}_3 + \mathbf{R}$

PBS Math is non-destructive

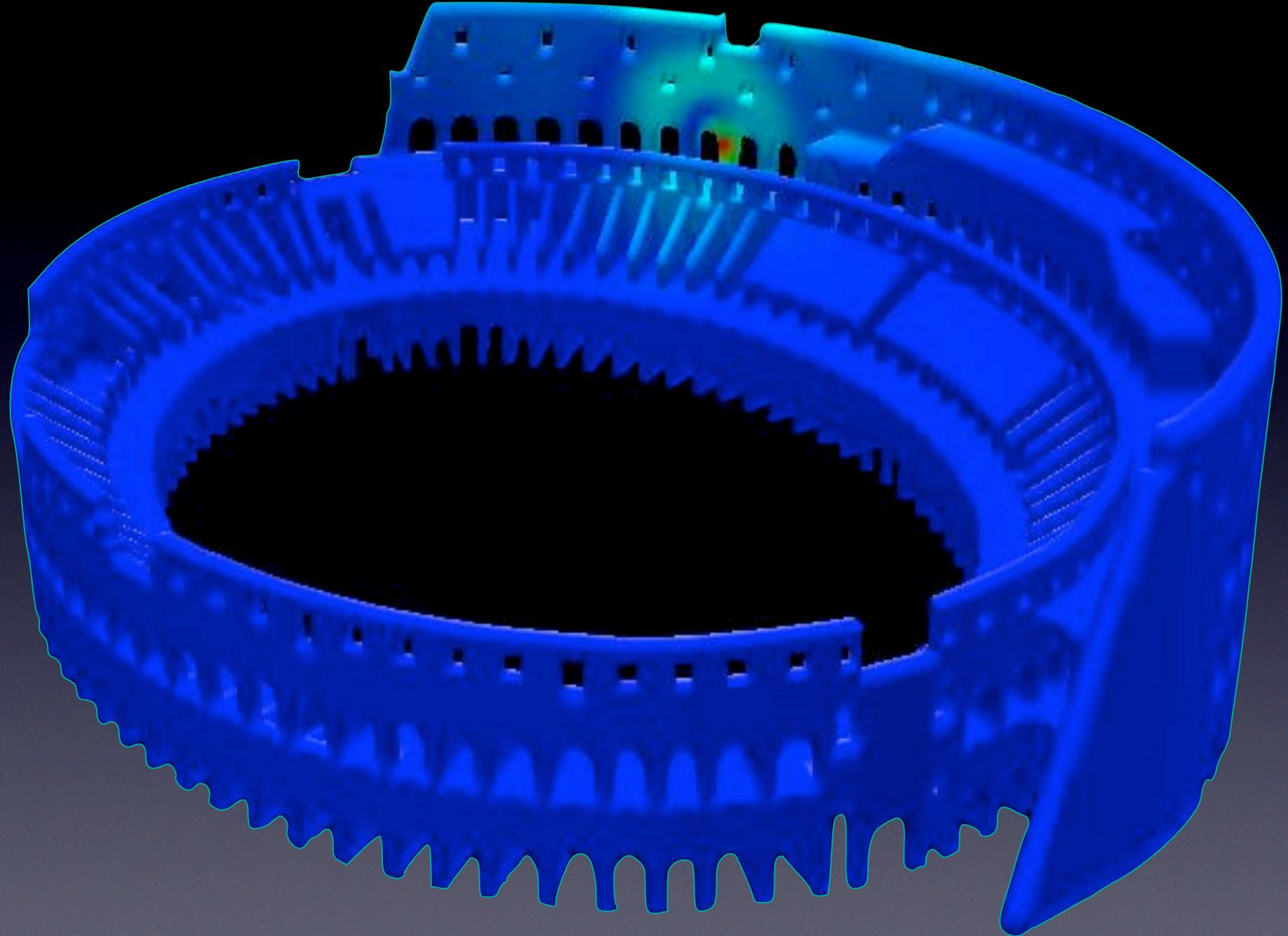




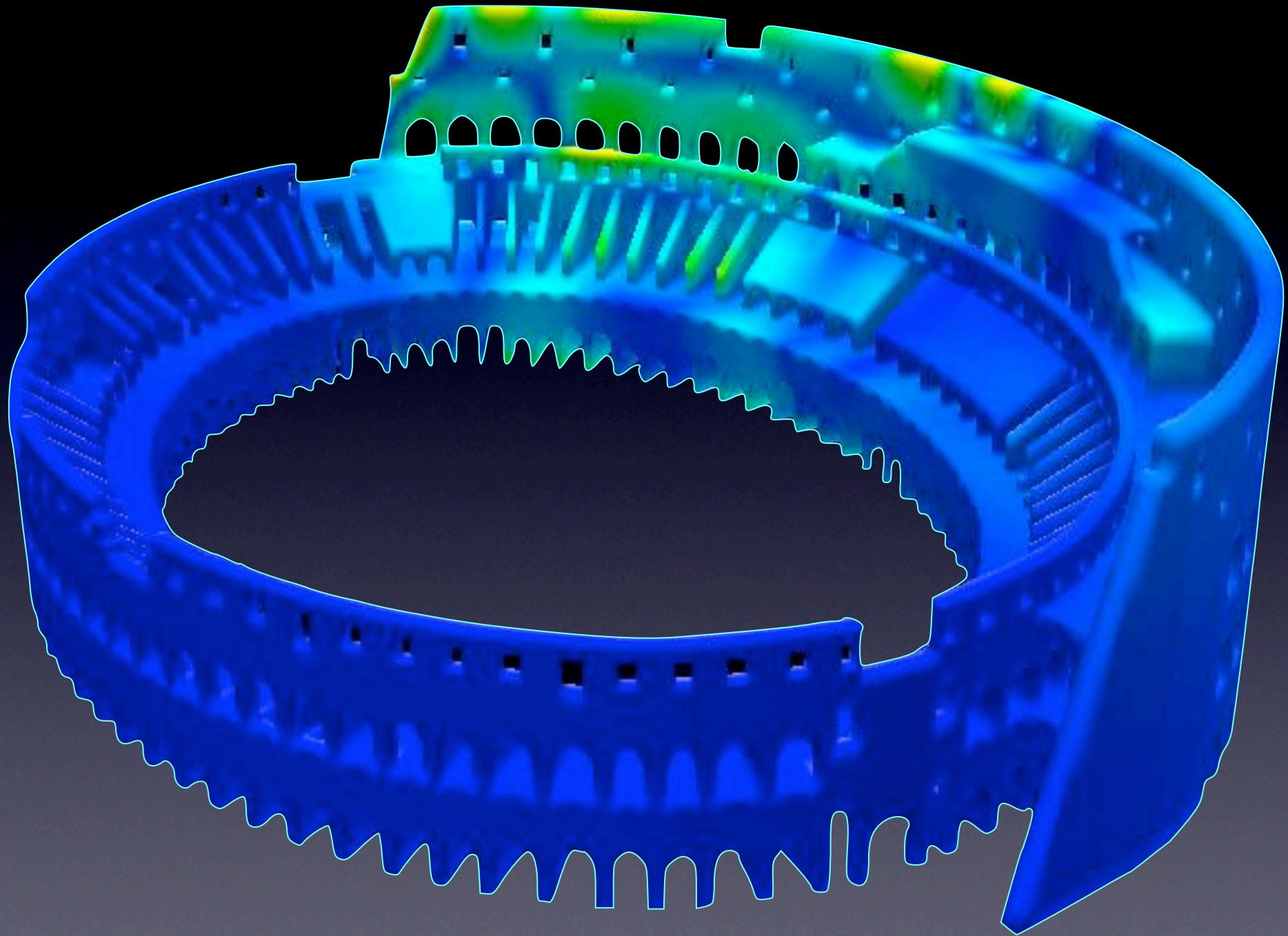




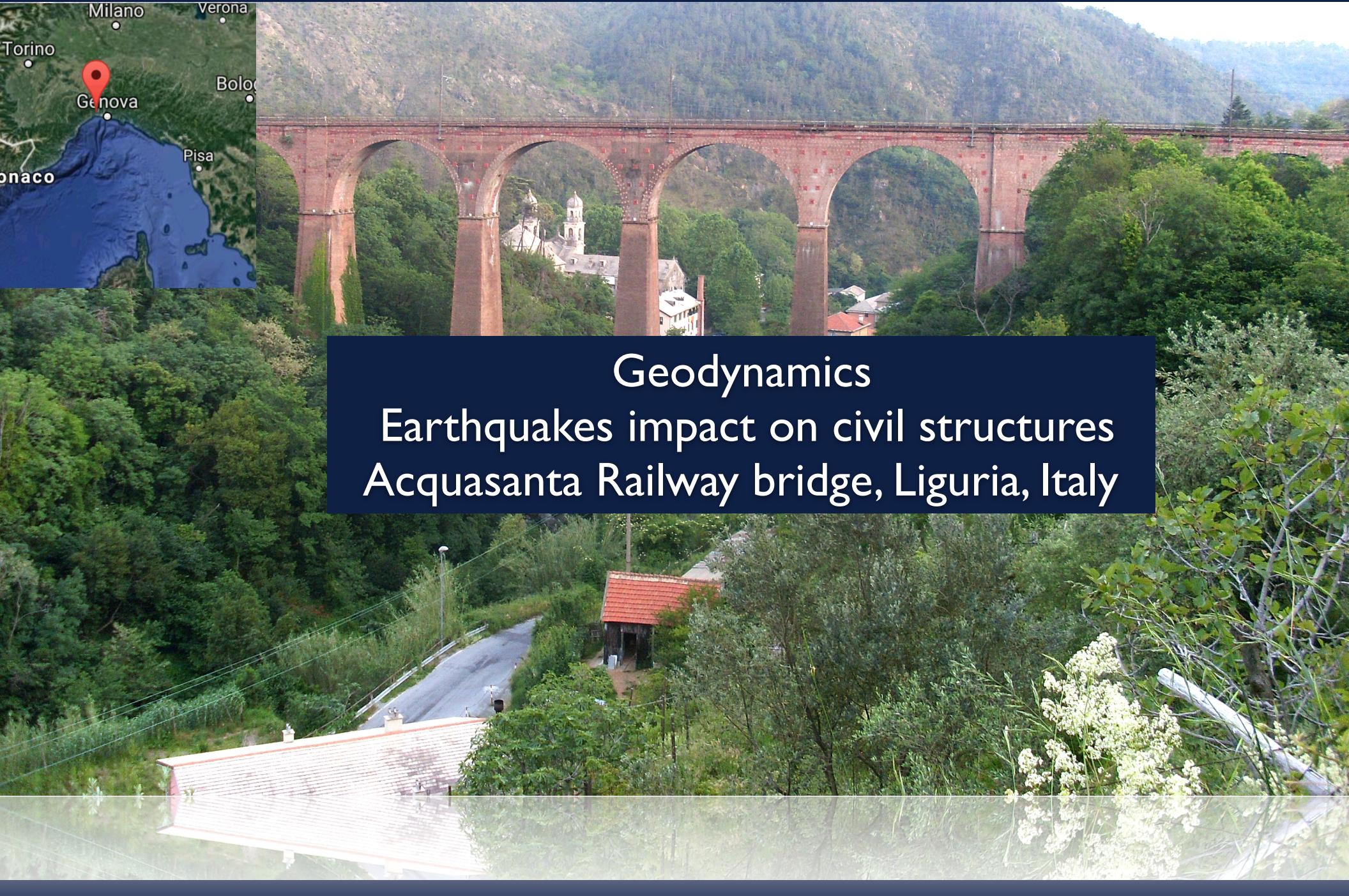
Maggio-Massidda-Fotia @ CRS4



Maggio-Massidda-Fotia @ CRS4



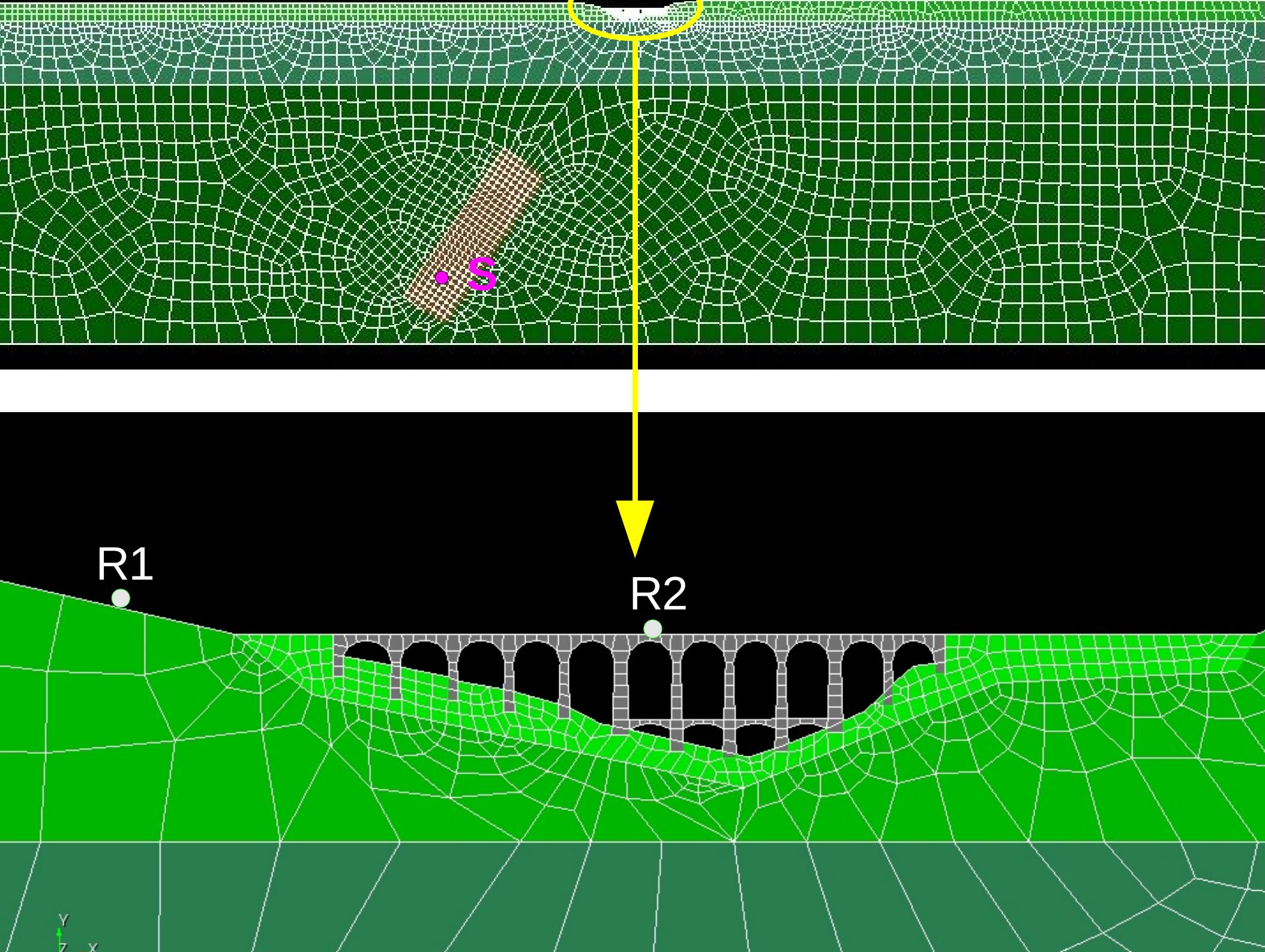
Maggio-Massidda-Fotia @ CRS4



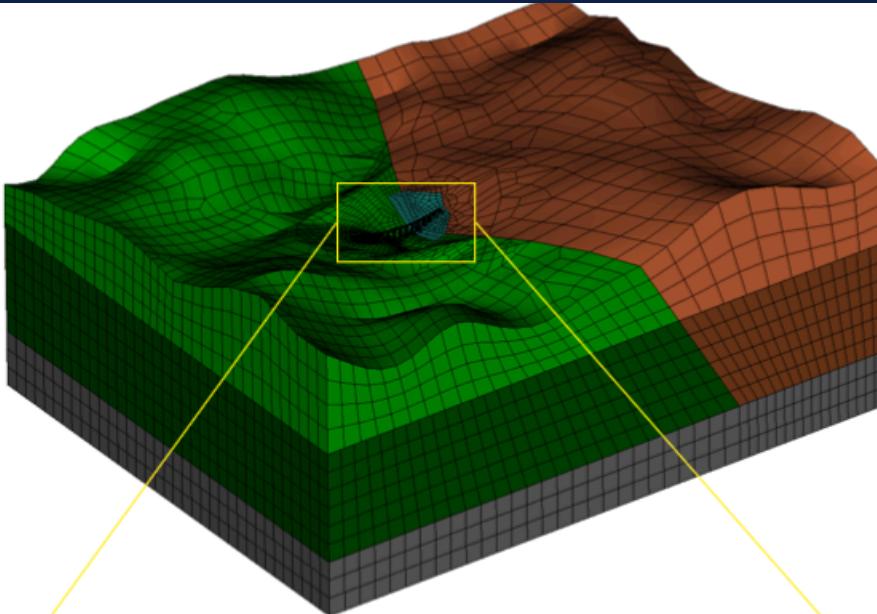
Geodynamics

Earthquakes impact on civil structures

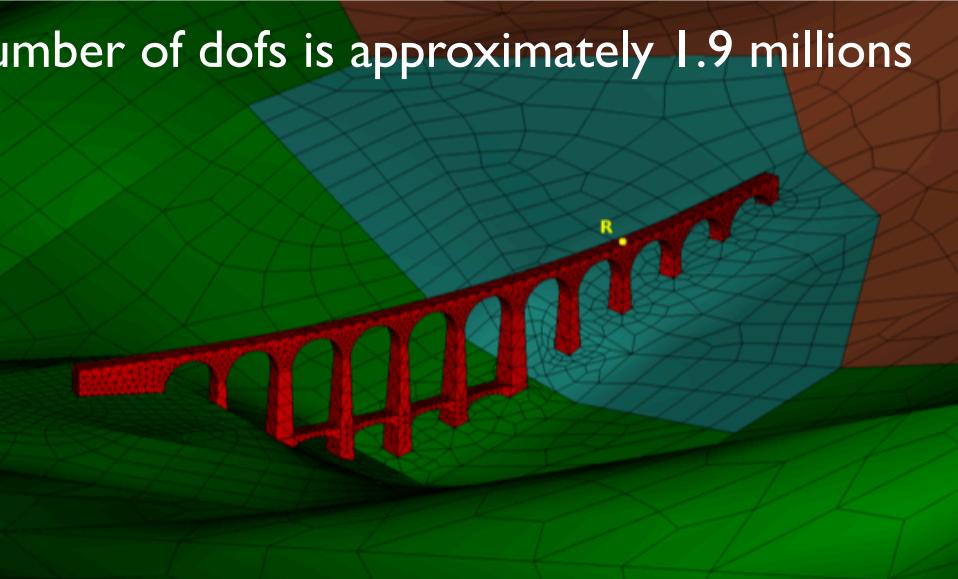
Acquasanta Railway bridge, Liguria, Italy



Acquasanta Railway bridge, Liguria, Italy



Number of dofs is approximately 1.9 millions



Material	$\rho [kg/m^3]$	$c_P [km/s]$	$c_S [km/s]$	Q
Serpentine Jurassic	2800	2.3	1.3	150
	—	—	—	—
	2400	1.1	2.4	125
Calceistic Jurassic	2800	2.3	1.3	150
	—	—	—	—
	2500	1.8	2.5	150
Alluvial basin	1925	0.3	0.17	25
Bridge	1750	1.22	0.72	50

- Complex topography
- Presence of a vertical subfault that divide the Serpentine and the Calceistic rocks
- Several piers of the bridges rest on a superficial alluvium deposit.
- Broad variability in the spatial scales (hundreds of meters in the geological region — centimeters in the bridge)
- Seismic source: double couple point located at (100,0,-300)m

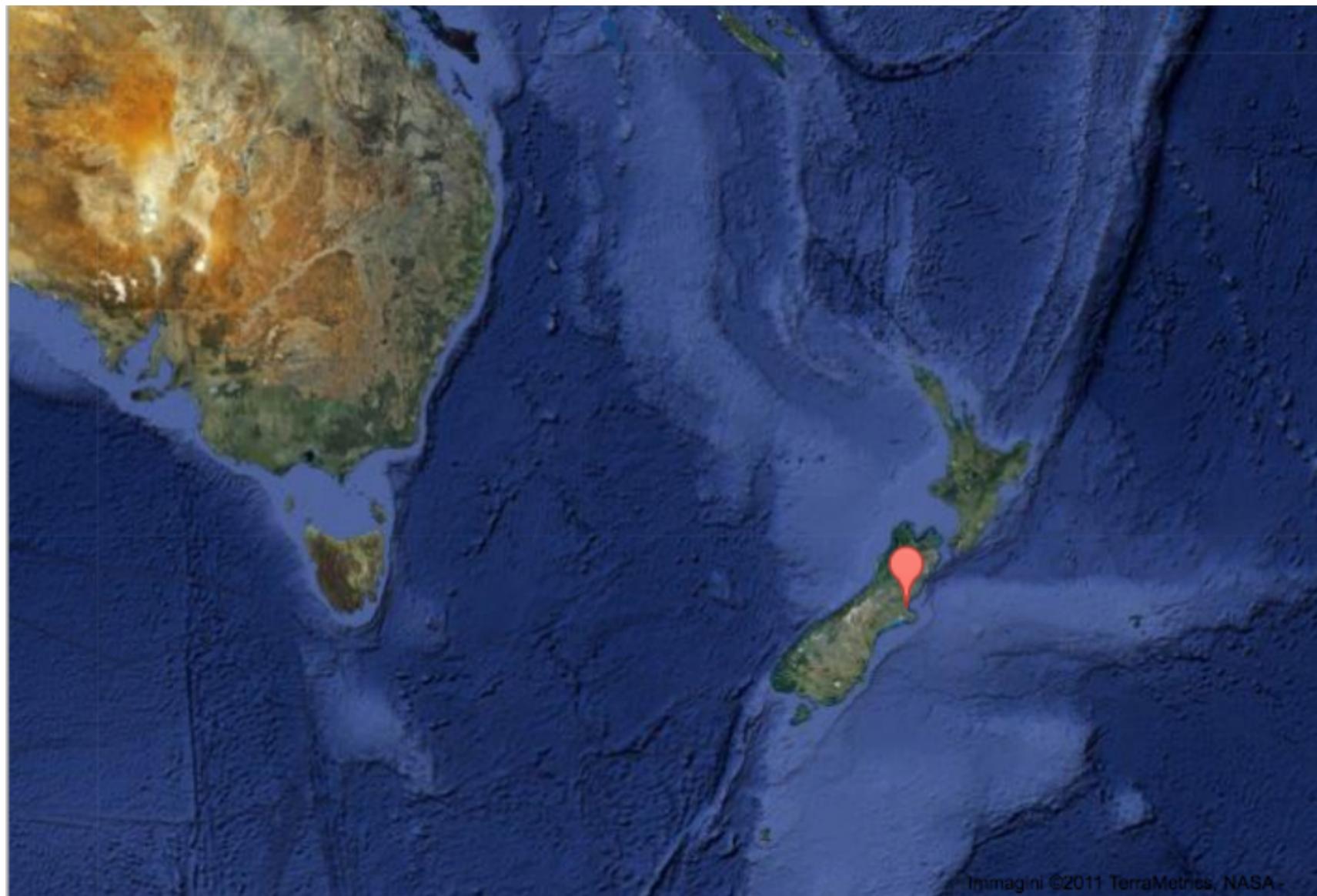
Acquasanta Railway bridge, Liguria, Italy

$t = 0.0 \text{ s}$



In collaboration with DICA (Politecnico di Milano)

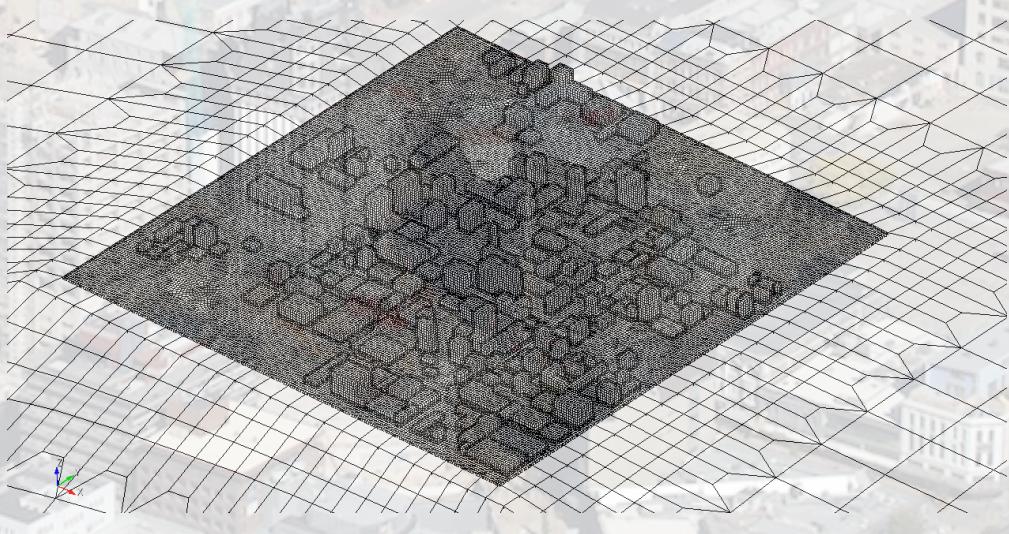
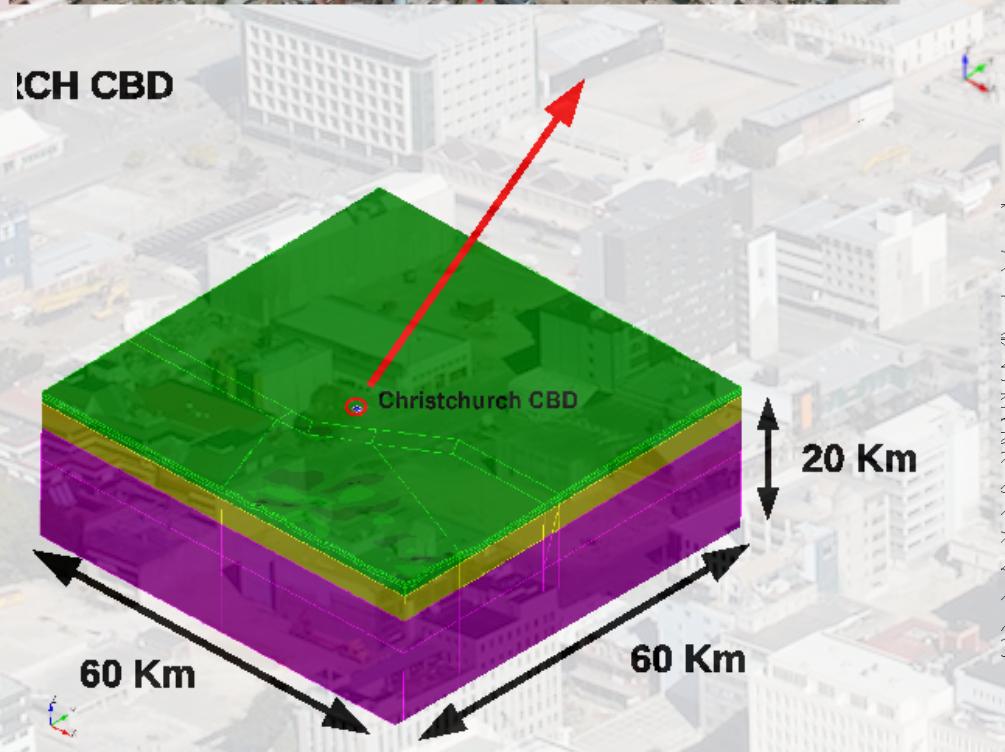
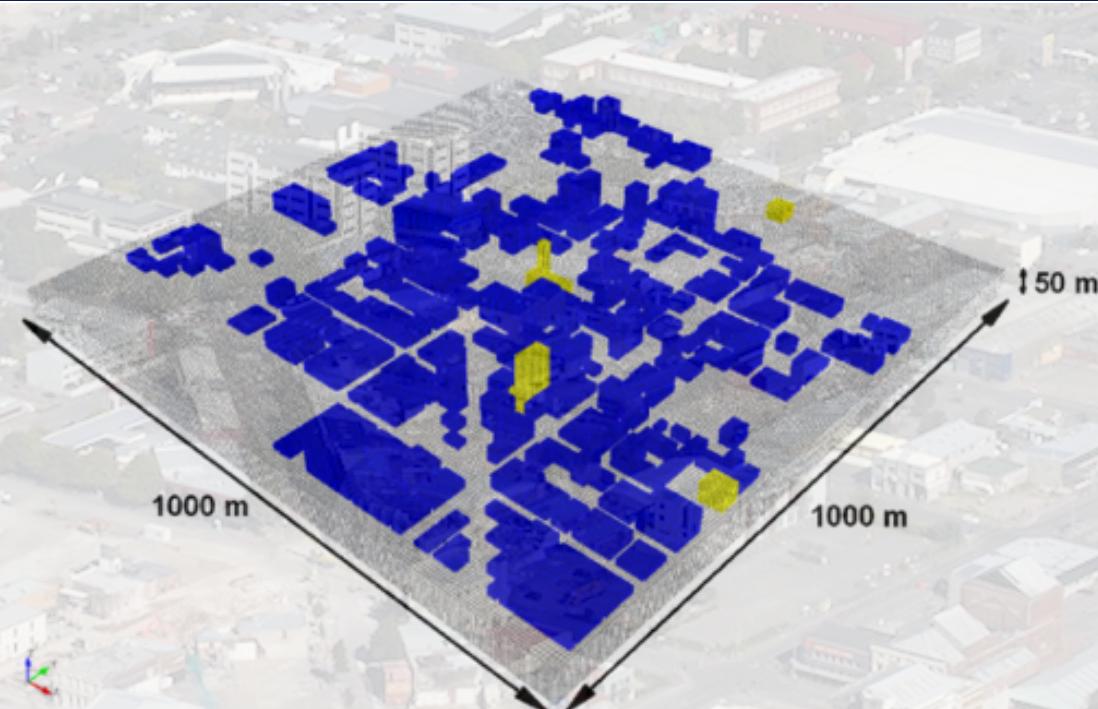
Christ Church, New Zealand

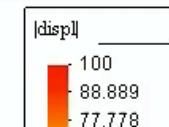
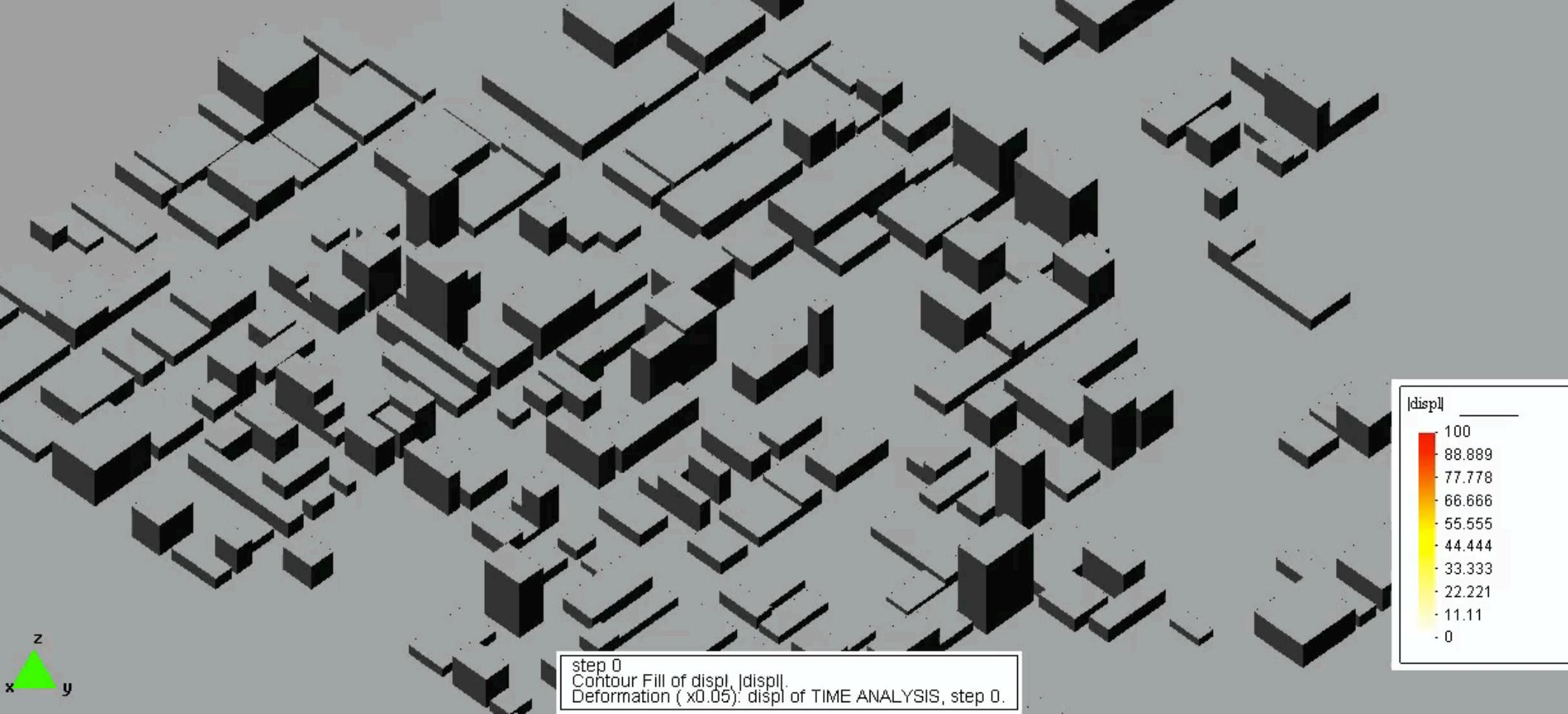


Christ Church, New Zealand (22 February 2011)

In collaboration with DICA (Politecnico di Milano)

Christchurch Central Business District: site-city interaction effects

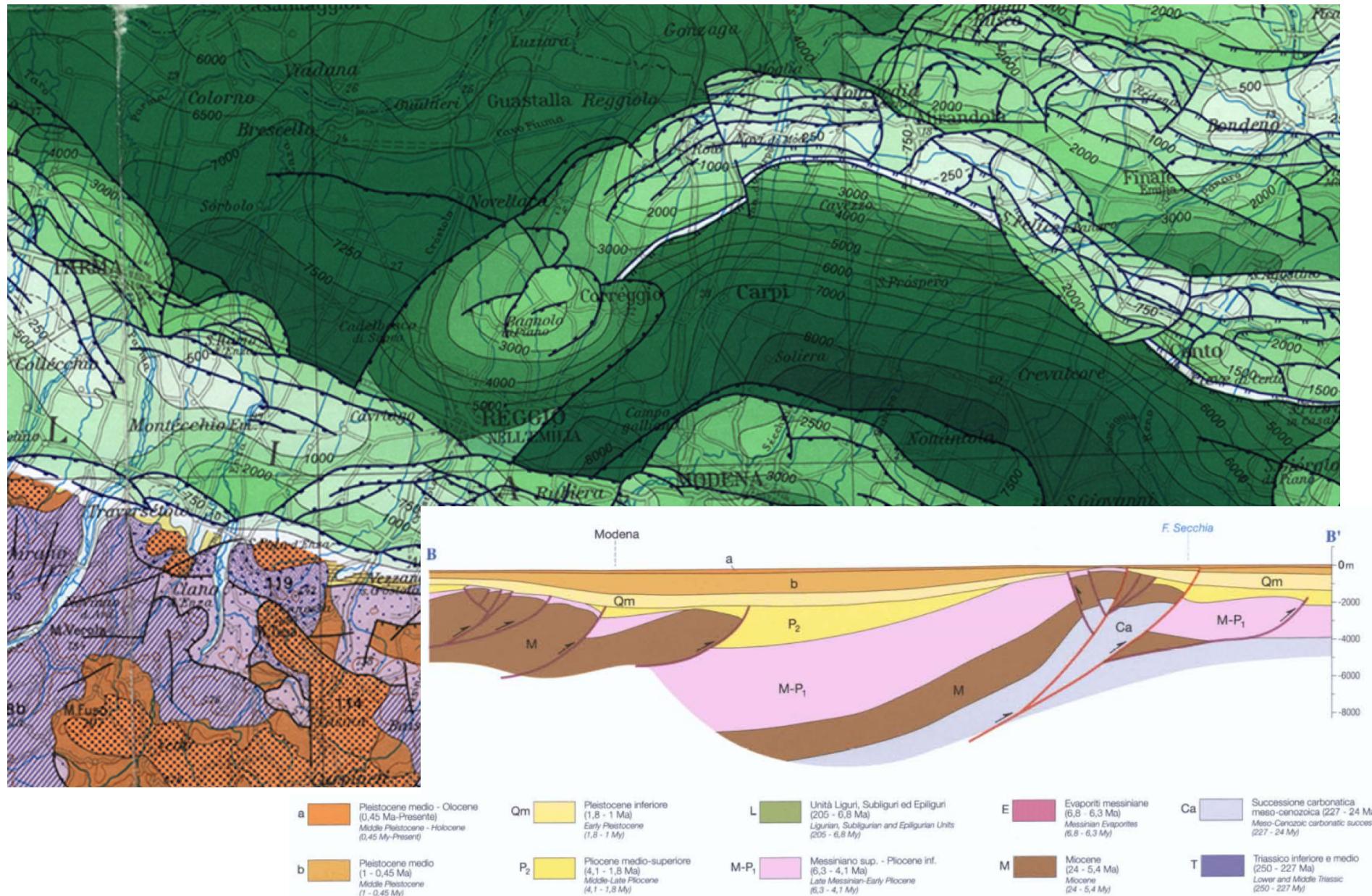




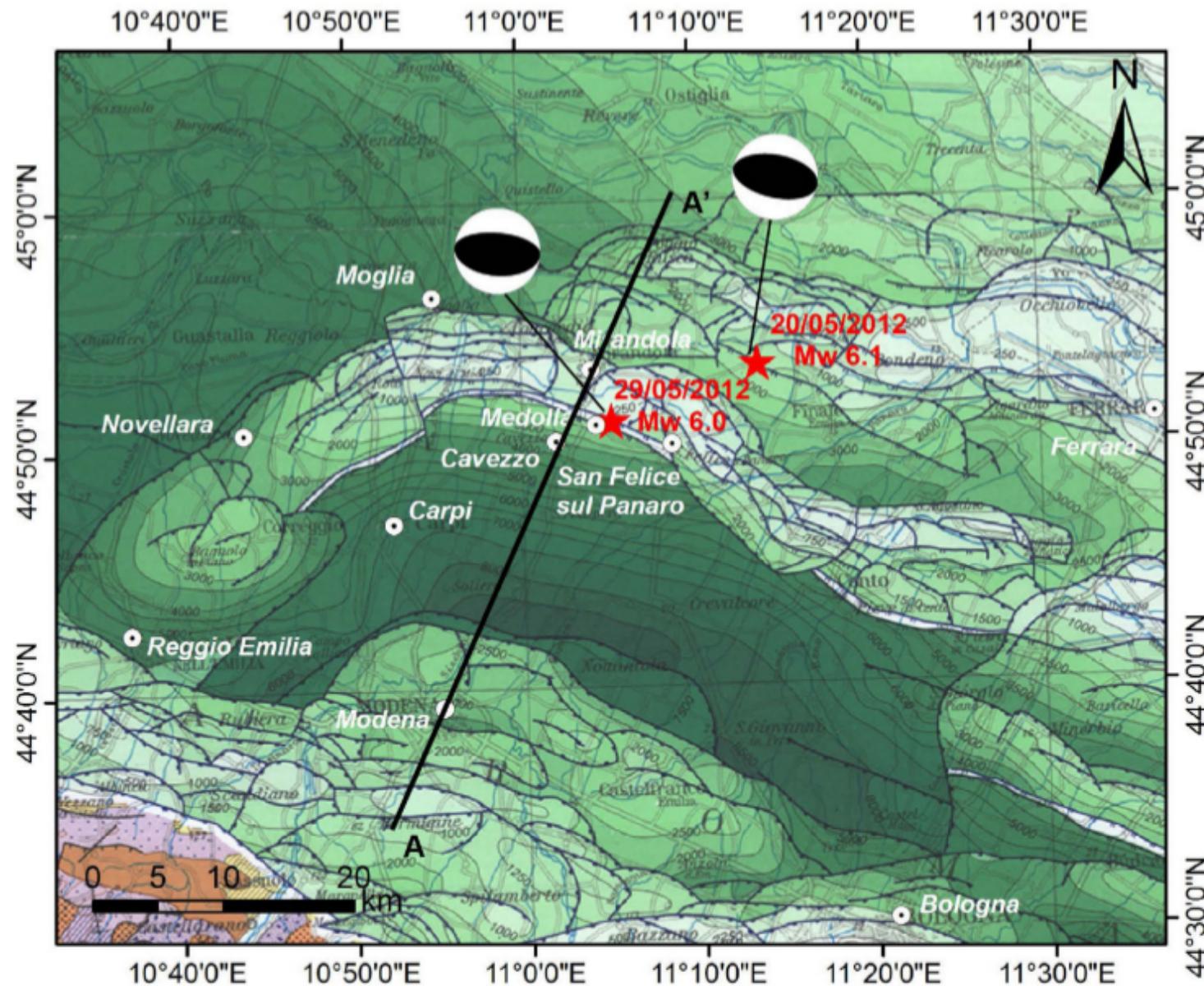


Courtesy of G. Penna

Emilia earthquake, 29.05.2012, M_w 6.0

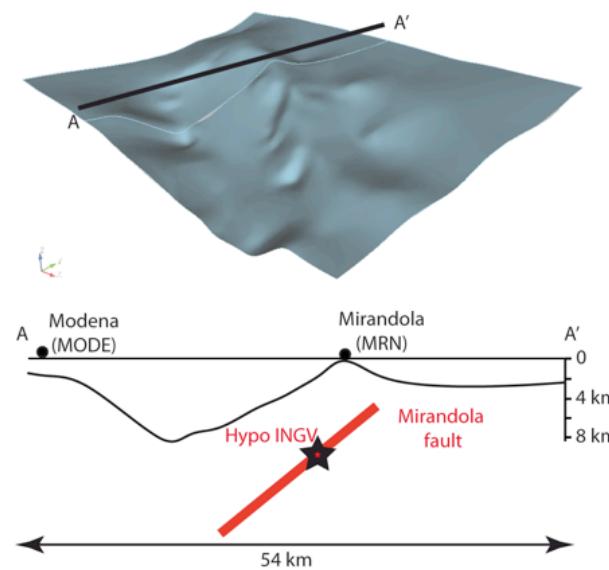
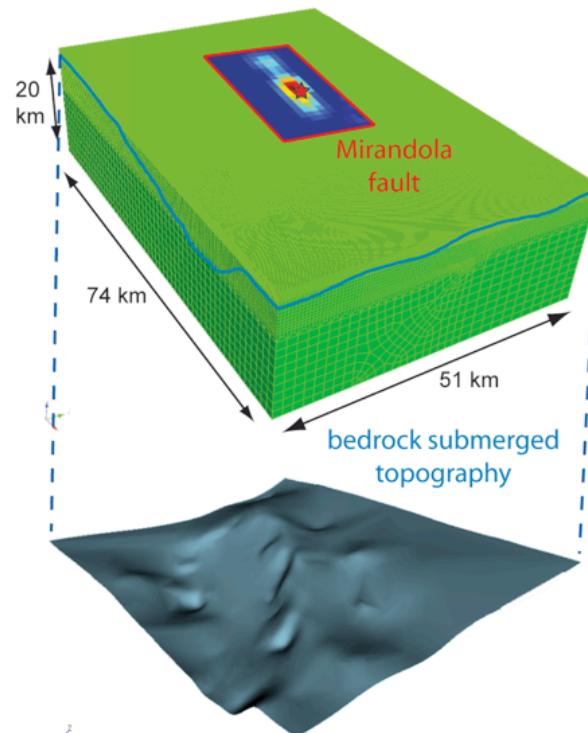
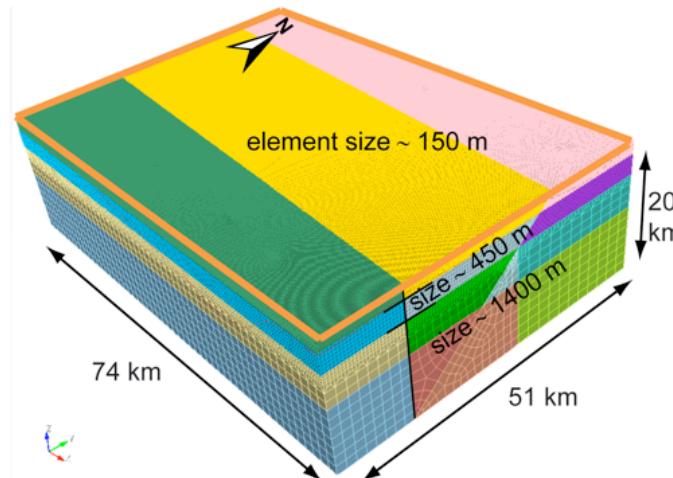
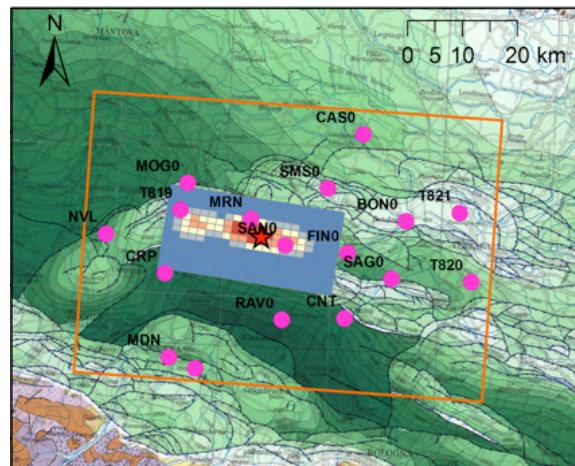


Emilia earthquake, 29.05.2012, M_w 6.0



Epicenter areas of the main shock 29.05 (M_w 6.1) and 20.05 (M_w 6.0).

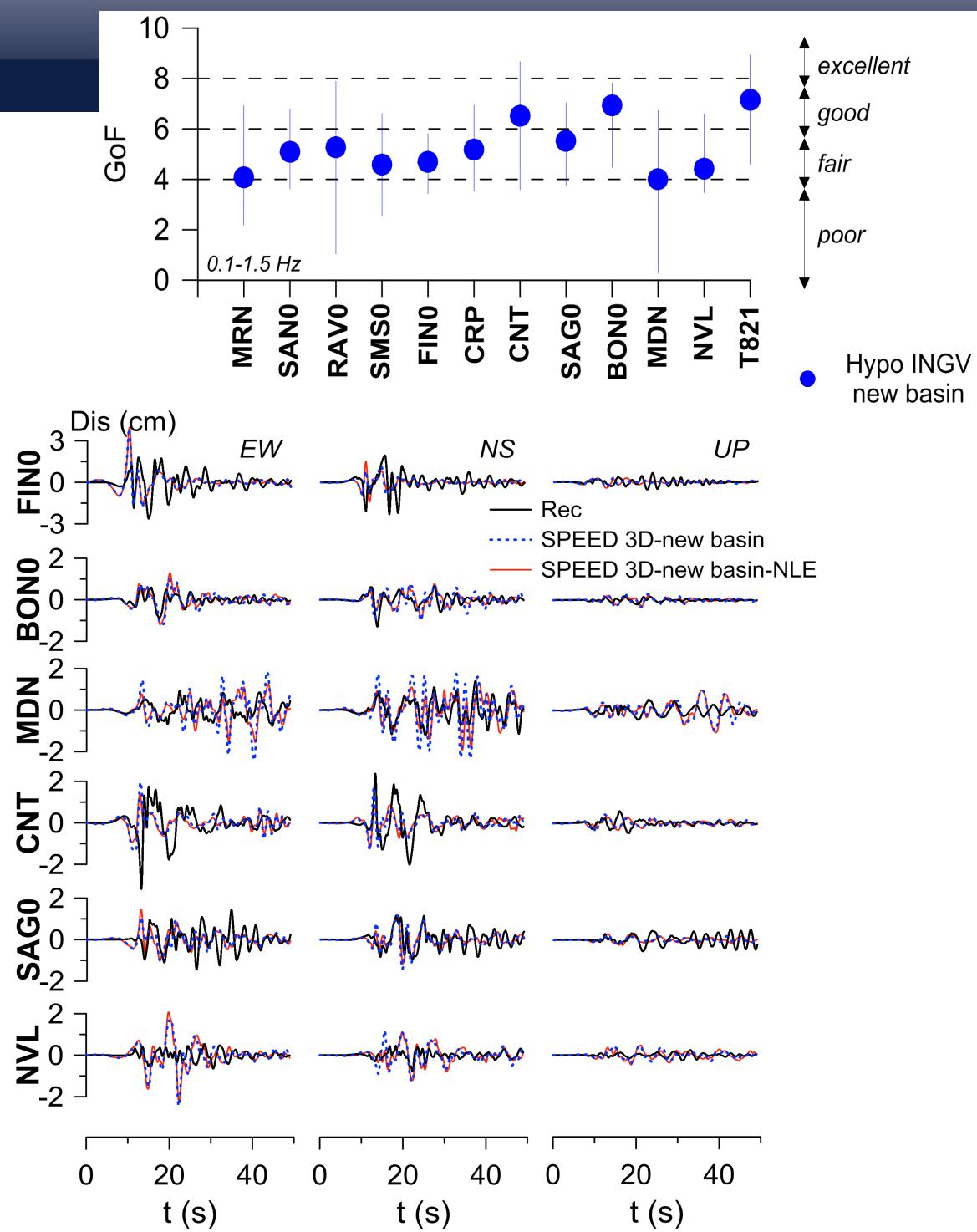
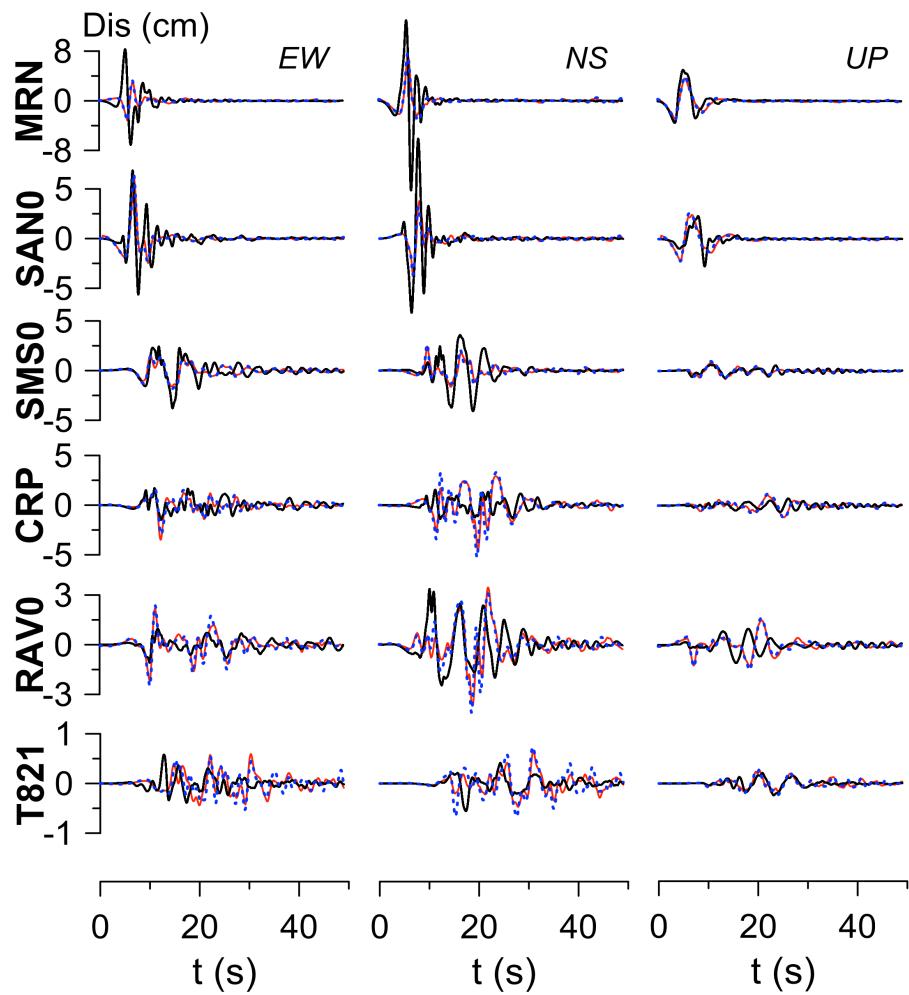
Emilia earthquake, 29.05.2012, M_w 6.0



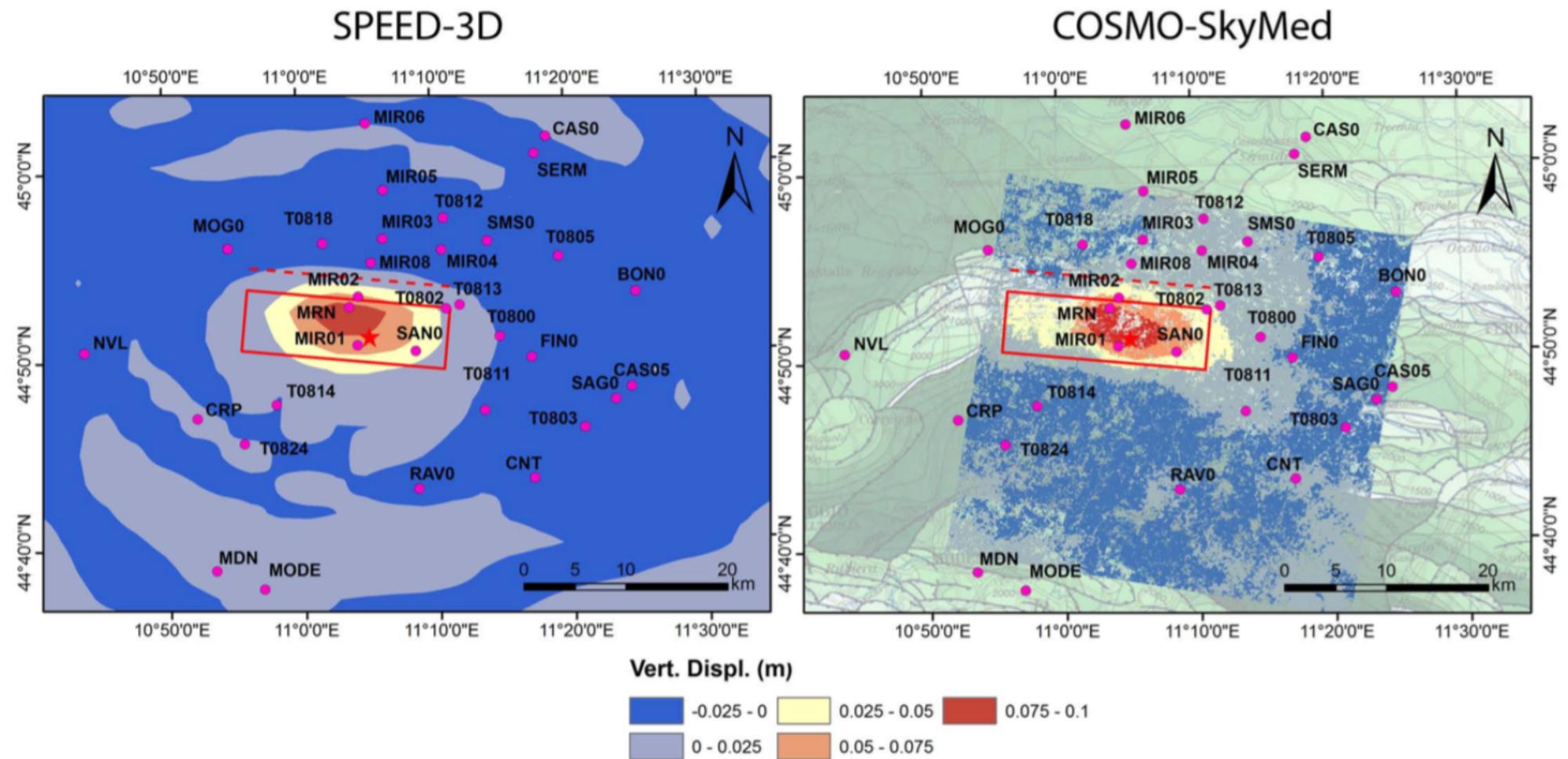
Number of dofs is approximately 150 millions

Validation of numerical results

Comparison between recorded (black) and simulated seismograms.
12 selected stations, three components of the velocity.



Comparison with satellite data



Map of permanent ground uplift simulated by SPEED (left) and observed by COSMO-SkyMed InSAR processing (right)

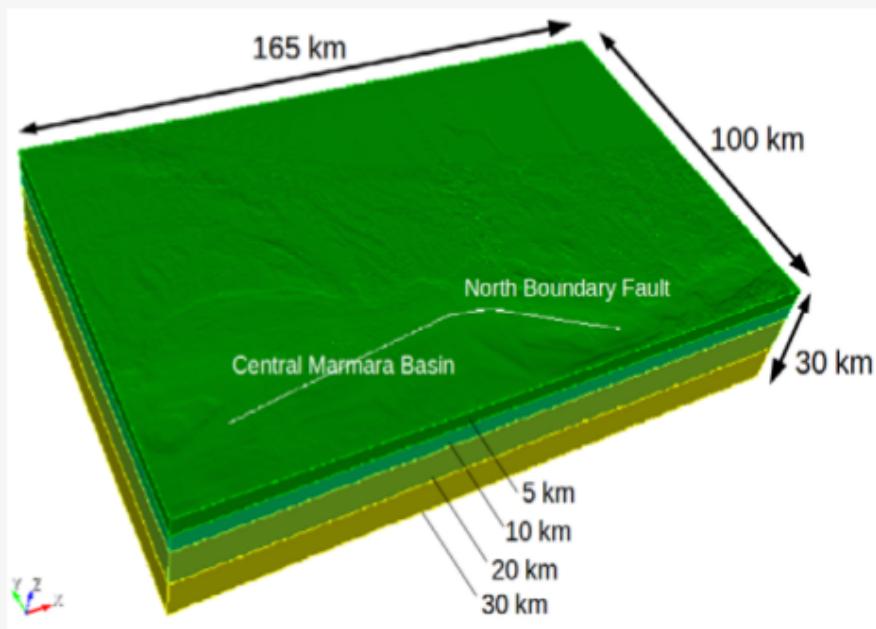
Good agreement between simulated and observed satellite data



Istanbul case study

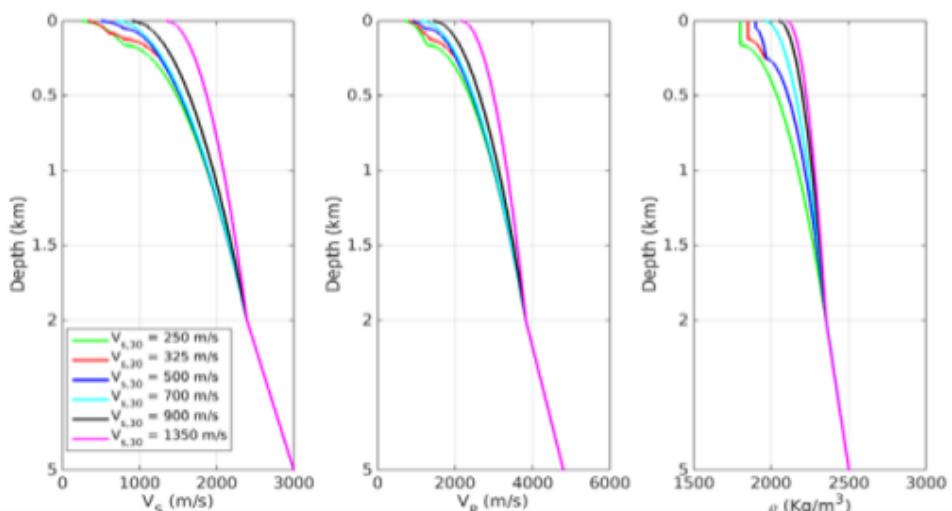
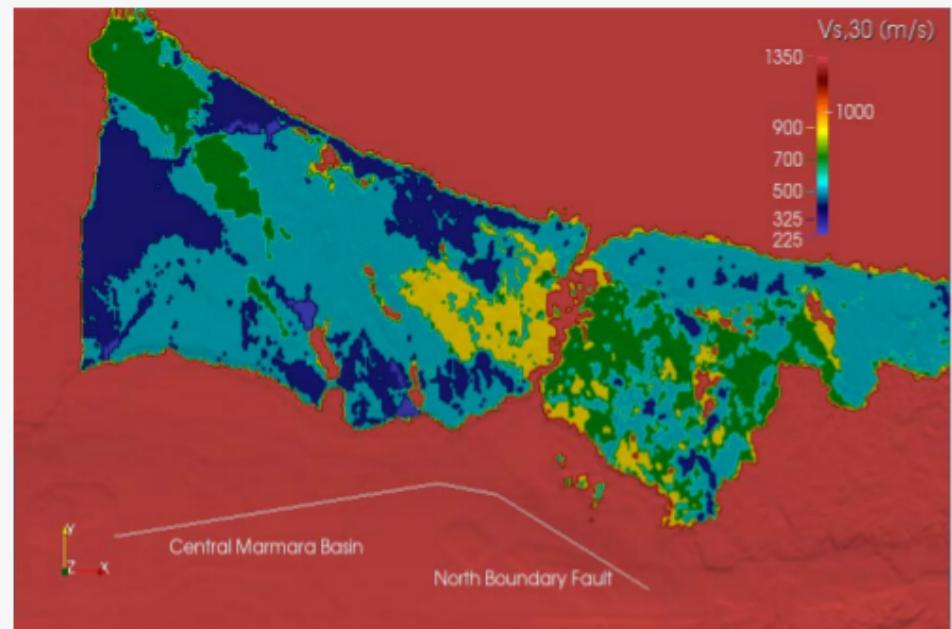
Istanbul case study

Computational domain of the Istanbul region adopted in the present work. Fault system (CMB and NBF) included in the domain as well as topography and bathymetry model

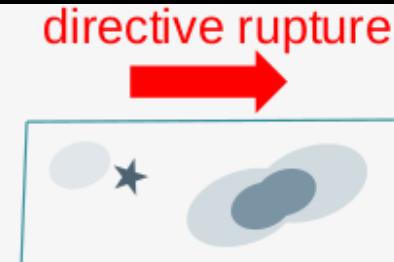
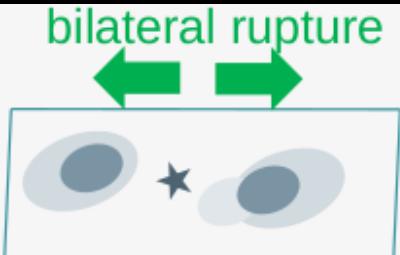


$f_{max} = 1.5 - 2 \text{ Hz}$
hexahedral elements = 2,257,482
degrees of freedom = 475 million
Min. element size = 180 m
Max. element size = 600 m (at 2 km depth)

VS,30 classes defined according to Özgül, 2011.



The case study: Istanbul



Grazie